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Operating Instructions

OI/TTF350-EN

Field mounted Temperature Transmitters TTF350

HART® FIELD COMMUNICATIONS PROTOCOL

Field mounted Temperature Transmitters
TTF350

Operating Instructions

OI/TTF350-EN

08.2007

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1 Safety

1.1 General Safety Information

The “Safety” chapter provides an overview of the safety aspects to be observed for the operation of the device.

The device is built based on state-of-the-art technology and is operationally safe. It was tested and left the factory in a proper state. The requirements in the manual as well as the documentation and certificates must be observed and followed in order to maintain this state for the period of operation.

The general safety requirements must be complied with completely during operation of the device. In addition to the general information, the individual chapters of the manual contain descriptions about processes or procedural instructions with specific safety information.

Only the observance of all safety information enables the optimal protection of personnel as well as the environment from hazards and the safe and trouble-free operation of the device.

1.2 Intended use

This device is intended for the following uses:

- To measure the temperature of fluid, pulpy or pasty substances and gases or resistance/voltage values.

The following items are included in the intended use:

- Read and follow the instructions in this manual.
- Observe the technical ratings (refer to the section “Technical data” or data sheet).

Repairs, alterations and enhancements or the installation of replacement parts is only permissible as far as described in the manual. Further actions must be verified with ABB Automation Products GmbH. Excluded from this are repairs performed by ABB-authorized specialist shops.

1.3 Technical limits

The device is designed for use exclusively within the stated values on the name plate and in the technical specifications (see "Technical Specifications” chapter and/or data sheet). These must be complied with accordingly, e.g.:

- The maximum operating temperature may not be exceeded.
- The permitted operating temperature may not be exceeded.
- The housing protection system must be observed.

1.4 Warranty provision

A use contrary to the device's stipulated use, disregarding of this manual, the use of under-qualified personnel as well as unauthorized alterations excludes the manufacturer of liability from any resulting damages. The manufacturer's warranty expires.

1.5 Labels and symbols

1.5.1 Symbols and warnings

Danger – <Serious damage to health / risk to life>

One of these symbols in conjunction with the "Danger" warning indicates an imminent danger. If it is not avoided, death or serious injury will result.

Warning – <Bodily injury>

The symbol in conjunction with the "Warning" message indicates a possibly dangerous situation. If it is not avoided, death or serious injury could result.

Caution – <Slight injuries>

The symbol in conjunction with the "Caution" message indicates a possibly dangerous situation. If it is not avoided, slight or minor injury can result. May also be used for property damage warnings.

Notice – <Property damage>!

The symbol indicates a possibly damaging situation. If it is not avoided, the product or something in its area can be damaged.

Important

The symbol indicates operator tips or especially useful information. This is not a message for a dangerous or damaging situation.

1.5.2 Name plate

The model plate is located on the transmitter housing.

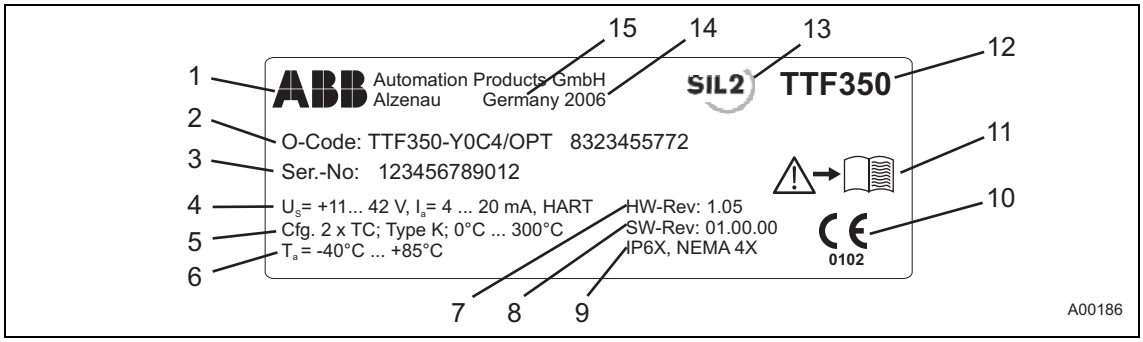


Fig. 1

1 Manufacturer of transmitter
2 Order code with SAP no.
3 Serial number
4 Approved power supply, current communications protocol
5 Configured parameters
6 Permissible ambient temperature
7 Hardware version
8 Software version
9 Level of protection
10 CE mark (EC conformity)
11 Refer to product documentation
12 Transmitter model
13 SIL mark
14 Year of manufacture
15 Country

Important

The temperature range on the model plate (6) refers only to the permissible ambient temperature range for the transmitter and not to the measuring element used in the measuring inset.

1.6 Operator liability

Before the use of corrosive and abrasive materials to be measured, the operator must clarify the resistance of all parts that come into contact with the materials to be measured. ABB will gladly support you with the selection, however, cannot accept any liability.

The operators must strictly observe the applicable national regulations in their countries with regards to installation, function tests, repairs, and maintenance of electrical devices.

1.7 Personnel qualification

The installation, commissioning and maintenance of the device may only be carried out through trained specialist personell authorized by the plant operator. The specialist personnel must have read and understood the manual and comply with its instructions.

1.8 Returning devices

Use the original packaging or a suitably secure packaging for returning the device for repair or for recalibration. Include the properly filled out return form (see attachment) with the device.

According to EC guidelines for hazardous materials, the owner of hazardous waste is responsible for its disposal or must observe the following regulations for its shipping:

All delivered devices to ABB Automation Products GmbH must be free from any hazardous materials (acids, alkali, solvents, etc.).

1.9 Disposal

ABB Automation Products GmbH actively promotes environmental consciousness and has an operational management system in accordance with DIN EN ISO 9001:2000, EN ISO 14001:2004 and OHSAS 18001. Our products and solutions should have minimum impact on the environment and persons during manufacture, storage, transport, use and disposal.

This includes the environmentally friendly use of natural resources. Through its publications ABB conducts an open dialog with the public.

This product/solution is manufactured from materials that can be reused by specialized recycling companies.

1.9.1 Information on WEEE directive 2002/96/EC (Waste Electrical and Electronic Equipment)

This product/solution is not subject to the WEEE directive 2002/96/EC and relevant national laws (e.g., ElektroG in Germany).

Dispose of the product/solution directly in a specialized recycling facility and do not use the municipal garbage. Only privately used products may be disposed of in the municipal garbage according to the WEEE directive 2002/96/EC. Proper disposal prevents negative effects on people and the environment, and supports the reuse of valuable raw materials.

If it is not possible to dispose of old equipment properly, ABB Service can accept and dispose of returns for a fee.

1.10 Transport safety information

Observe the following information:

- Do not expose the device to moisture during transport. Pack the device accordingly.
- Pack the device so that it is protected from vibration during transport, e.g. through air-cushioned packaging.

Check the devices for possible damage that may have occurred from improper transport. Damages in transit must be recorded on the transport documents. All claims for damages must be claimed without delay against the shipper and before the installation.

1.11 Electrical installation safety information

The electrical connection may only be performed by authorized specialist personnel according to the electrical plans.

Observe the electrical connection information in the manual, otherwise the electrical protection can be affected.

The secure isolation of contact-dangerous electrical circuits is only guaranteed when the connected devices fulfil the requirements of the DIN VDE 0106 T.101 (basic requirements for secure isolation).

For secure isolation, run the supply lines separated from contact-dangerous electrical circuits or additionally isolate them.

1.12 Operating safety information

Before switching on, ensure that the specified environmental conditions in the “Technical Specifications” chapter and/or in the data sheet are complied with and that the power supply voltage corresponds with the voltage of the transmitter.

When there is a chance that safe operation is no longer possible, put the device out of operation and secure against unintended operation.

2 Use in areas requiring ignition protection

Special regulations must be observed in explosion-protection zones for the auxiliary power connection, signal inputs/outputs and ground connection. Information on ignition protection in the separate chapters must be observed.

Caution! Potential damage to parts!

All parts must be installed in accordance with manufacturer information and relevant standards and regulations.

Startup and operation must be performed in accordance with ATEX 137 or BetrSichV (EN60079-14).

2.1 Approvals

The approvals for use of the TTF350 temperature transmitter in explosion-protection areas can be found in the section "Approvals".

2.2 Ground

If for functional reasons, the intrinsically safe circuit has to be grounded by connection to the equipotential bonding system, it may only be grounded at a single location.

2.3 Interconnection

If transmitters are operated in an intrinsically safe circuit, proof that the interconnection is intrinsically safe must by provided in accordance with DIN VDE 0165/08.98 (EN 60 079-14/1997 and IEC 60 079-14/1996). In general, intrinsically safe circuits require proof of interconnection.

2.4 Configuration

TTF350 temperature transmitters can be installed in the explosion-protection area in compliance with the proof of interconnection and directly in the explosion-protection area using approved handheld HART terminals (e.g., HC275) as well as by coupling an ignition-proof modem to the circuit outside the explosion-protection area.

2.5 Explosion-protection relevant information

For additional information, refer to the section “Explosion-protection relevant information”.

3 Design and function

TTF350 digital transmitters are communication-ready field devices with microprocessor-controlled electronics. For bidirectional communication, an FSK signal is superimposed on the 4 … 20 mA output signal via the HART protocol.

The graphic user interface (DTM) can be used to configure, poll and test transmitters on a PC-specific basis. Handheld terminals also support communication.

The transmitter is equipped with an LCD display. The LCD display is used to visualize the current process data. The four control buttons can be used to perform a local configuration.

For explosion-proof designs, the Ex design is described on a separate plate.

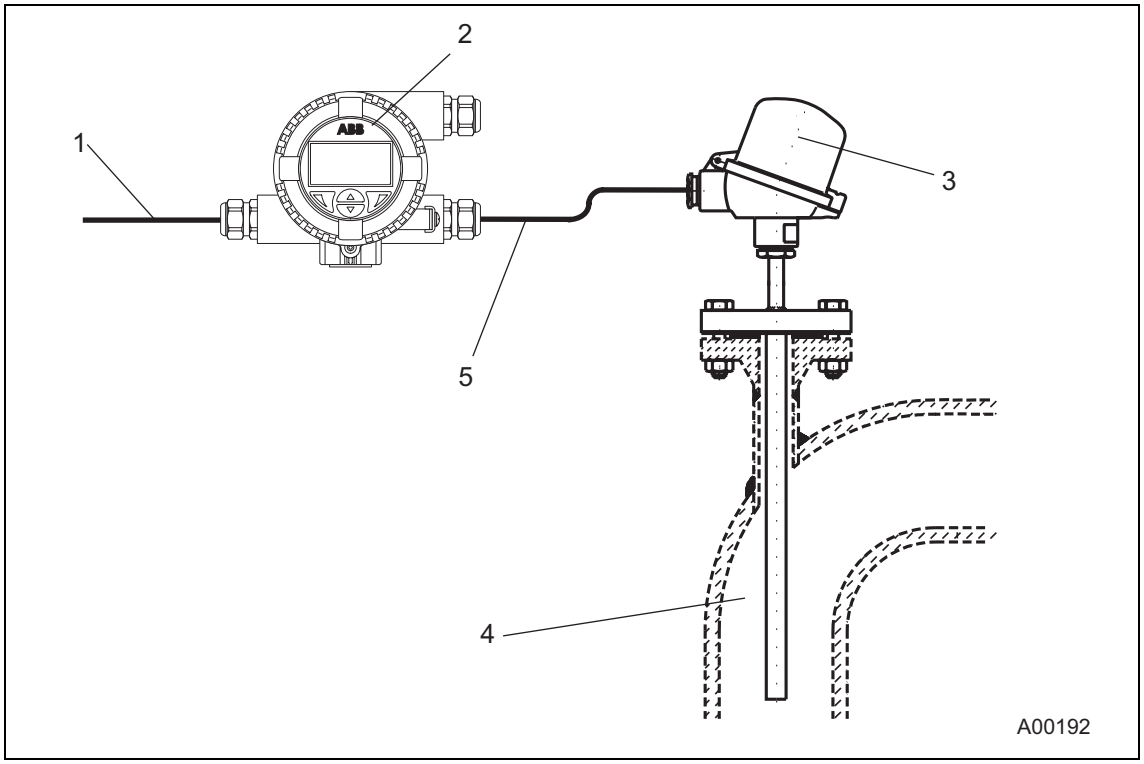


Fig. 2

1 Signal/power supply cable
2 Transmitter TTF350
3 Temperature sensor head
4 Processing pipe
5 Sensor connection cable

4 Installation

4.1 Installation options

There are two ways to install transmitters:

- Wall installation
- Pipe installation

Important

The transmitter is available with optional type B LCD display / configuration software.

4.1.1 Wall installation

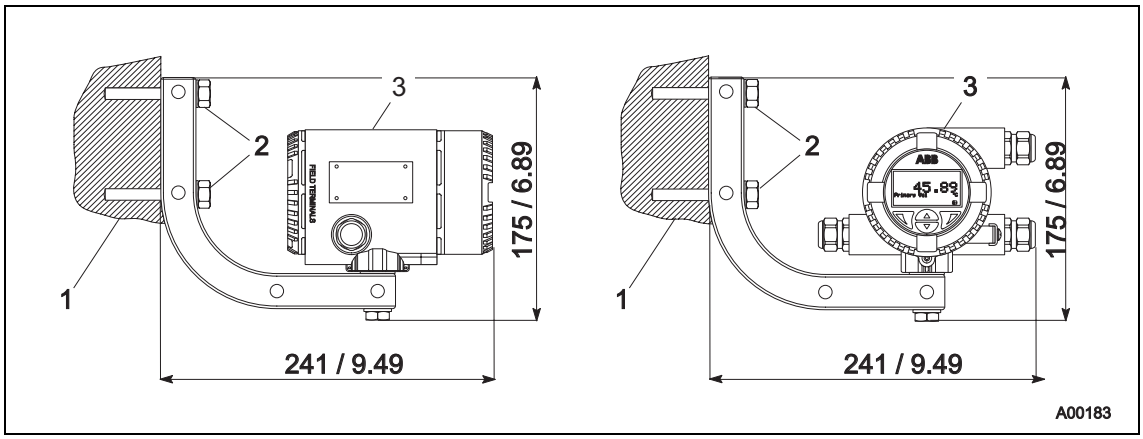


Fig. 3: Dimensions in mm/inches

1 Wall
2 Wall mount
3 Transmitter TTF350

1. Locate an installation site close to the temperature sensor head.

Warning - General hazards!

The transmitter can fall and be damaged if not firmly attached. There is also a risk that persons can be injured.

Install the wall mount on a sufficiently stable wall only.

2. Screw the transmitter to the wall mount.
3. Attach the wall mount securely with 2 screws (∅ 10 mm).

4.1.2 Pipe installation

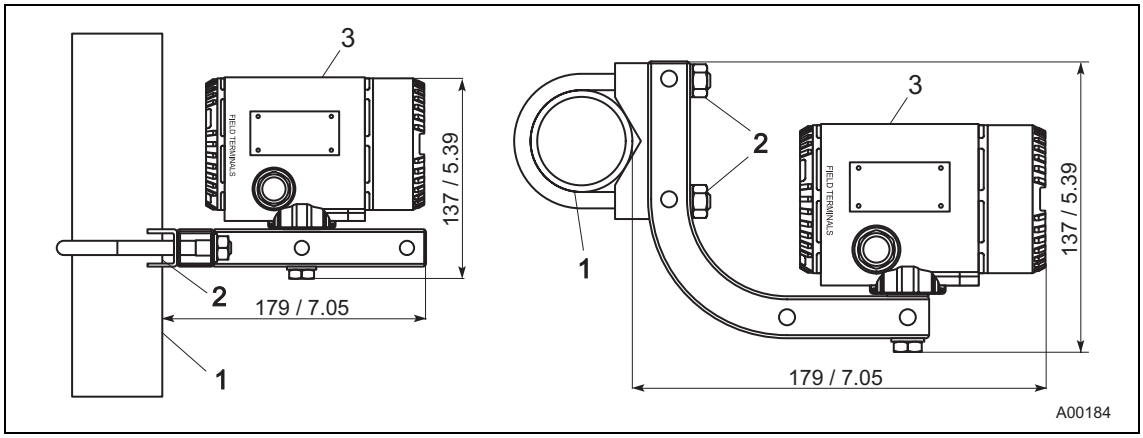


Fig. 4: Dimensions in mm/inches

1 Pipe (max. Ø 2 inches)
2 Pipe mount
3 Transmitter TTF350

1. Locate an installation site on a pipe close to the temperature sensor head.

Important
The pipe mount can be attached to a pipe with a maximum diameter of 2" (max. 60 mm).

2. Screw the transmitter to the pipe mount.
3 Attach the pipe mount securely to the pipe with 2 pipe clamps (∅ 10 mm).

Important
The wall and pipe installation set supports variable installation positions. A few examples of the different options are shown here. The mounting screw allows infinitely adjustable positioning (0° … 360°) of the housing.

4.2 Installing and aligning the optional LCD display with control buttons

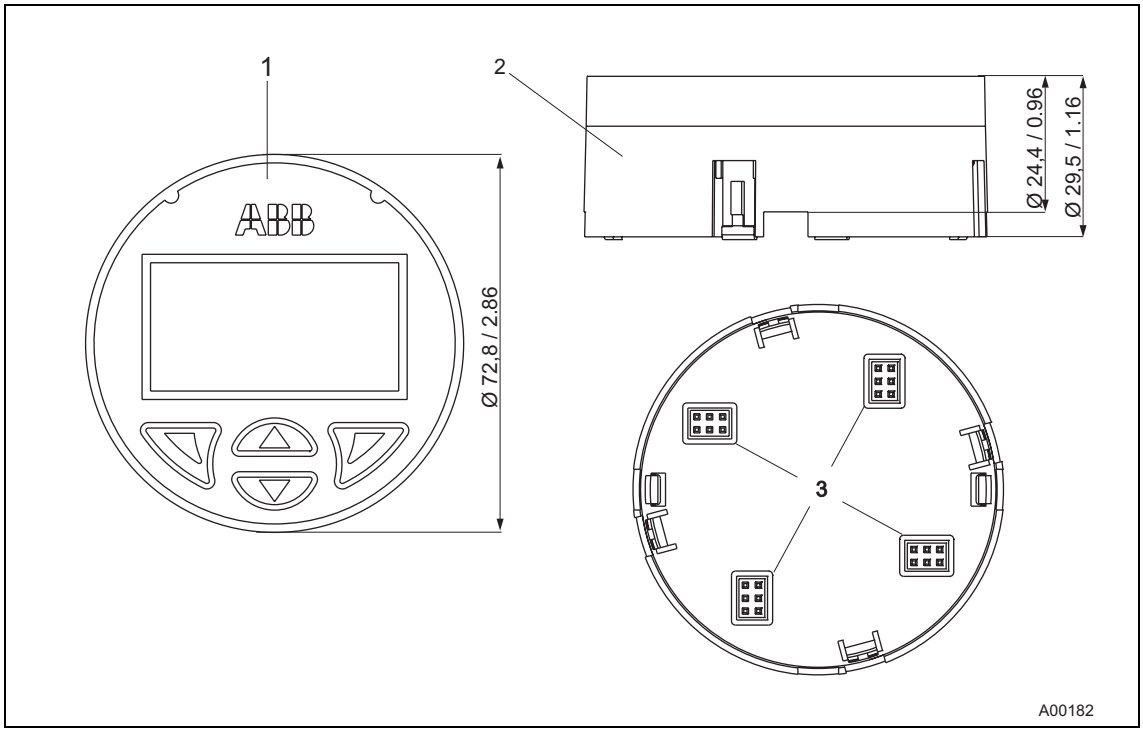


Fig. 5

1 Front view
2 Side view
3 Rear view of LCD display / plug positions

The LCD display is attached to the housing of the TTF350 transmitter.

1 Unscrew the housing cover for the transmitter.

2. Carefully remove the LCD display from the inset for the transmitter. The LCD display is held firmly in place. You might have to use the tip of a screwdriver to pry loose the LCD display. Avoid mechanical damage.
3. No tools are required to insert the LCD display, which can be mounted in 4 positions at 90 degree intervals to ensure the display is mounted properly and readable.
4. Screw on the housing cover for the transmitter.

5 Electrical connection

Warning – Electrical voltage risk!

Observe the corresponding instructions for the electrical installation. Only connect in dead-voltage state!

Since the transmitter has no switch-off elements, overvoltage protection devices, lightning protection or voltage separation capacity must be provided on the plant side.

Energy supply and signal are routed in the same line and are to be implemented as SELV or PELV circuit according to norm (standard version). In the ignition-proof version, the guidelines according to the ignition-proof norms are to be adhered to.

It must be checked whether the existing power supply corresponds with the specifications on the name plate and the technical specifications (see “Technical Specifications" chapter and/or data sheet).

Important

The electrical connection is carried out with the transmitter in the installed state.

The signal cable wires must be provided with wire end sleeves.

The cross-head screws of the connection terminals are tightened with a size 1 screwdriver (3.5 mm or 4 mm).

5.1 Conductor material

- Standard conductor material must be used for the power supply cable.
- The maximum peripheral wire cross section is 2.5 mm^2.

Caution! Potential damage to parts!

A rigid conductor material can result in wire breaks.

The connecting cable must be flexible.

Line length

From the lower edge of the housing (no cable gland) to the hole in the clamping area, an additional 100 mm of line is needed. An overall line length (without cable gland) of approx. 200 mm is required (approx. 100 mm bared).

5.2 Connection for power supply cable

Caution - Potential damage to parts!

Connecting the power supply cable with power switched on may result in a short circuit and potential damage to the transmitter.

The power must be switched off to connect the power supply cable.

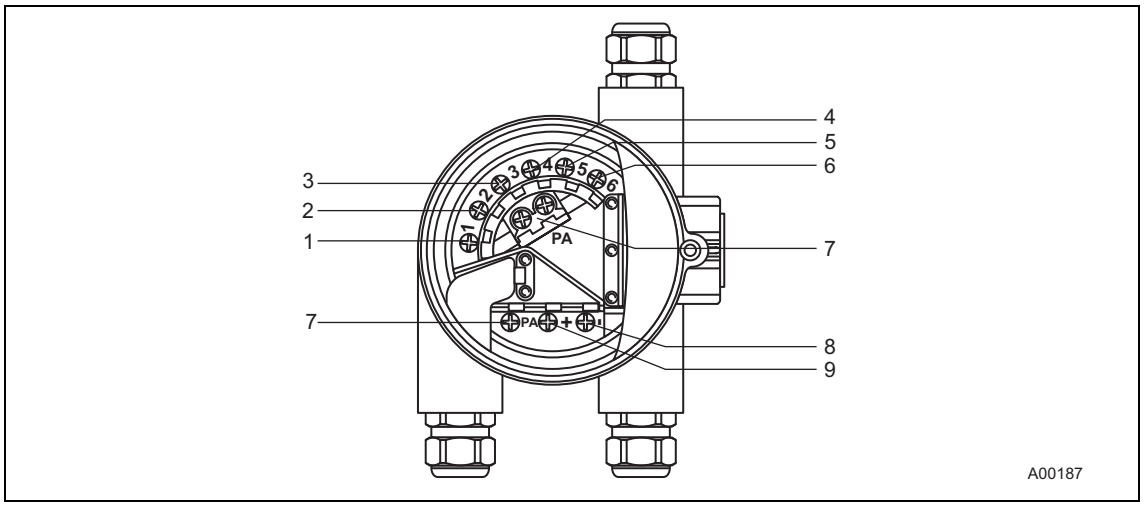


Fig. 6 Sensor and supply voltage terminal box of the TTF350 field device

1 … 6	Sensor connection	7	Shield
7 … 9	Signal/power supply connection	8	Minus
	11 ... 42 VDC / 4 … 20 mA	9	Plus
	11 … 30 VDC / 4 … 20 mA (Ex)		

1. Route the power supply cable through the cable gland into the housing of the transmitter. Then tighten the cable gland.
2. Strip the wires and attach wire end sleeves.
3. Release the clamping screws for the (+) and (-) terminals with the proper screwdriver. Make sure that the screws do not fall out.
4. Connect the (+) wire to the (+) terminal on the transmitter.
5. Connect the (-) wire to the (-) terminal on the transmitter.

The connection of the line shield is optional.

5.3 Connection for measuring element

Important

The model of the sensor connecting cable must correspond to the sensor model and configuration of the transmitter.

When connecting the transmitter and measuring inset (sensor) make sure for thermocouple sensors that the material of the sensor connecting cable corresponds to the thermocouple model.

1. Look for the connection type for the selected measuring element in the connection diagrams.
2. Release the clamping screws for terminals 1 to 6 using the proper screwdriver. Make sure that the screws do not fall out.
3. Insert the wires for the measuring element and sensor cable connection under the open terminals and carefully tighten the clamping screws for the connections.

5.4 Cable glands

5.4.1 TTF350 without cable gland

The cable diameter for the cable gland used must comply with requirements for IP / Nema 4x protection class. This must be checked during installation.

For delivery without cable gland (threads M20x1.5 or NPT 1/2"), the following points must be observed:

- Use cable glands acc. to version M20 x 1.5 or NPT 1/2".
- Observe information in data sheet / operating instructions for cable gland used.
- Check the working temperature for the cable gland used.
- Check the IP protection class IP66 / 67 or NEMA 4X of the cable gland in used.
- Check the explosion protection relevant information for the cable gland used acc. to manufacturer's data sheet or Ex certificate.
- The cable gland used must be approved for the cable diameter (IP protection class).
- For tightening torque, observe information in data sheet / operating instructions for cable gland used.

5.4.2 TTF350 EEx d models without cable gland

For delivery of the product variants TTF350-E3... (ATEX EEx d / hermetically sealed) and TTF350-E4....(ATEX EEx d and EEx ia or hermetically sealed and intrinsically safe) without cable gland an approved ATEX EEx d cable gland must be used according to EN 50018.

The explosion protection relevant information for the cable glands (M20*1.5 6H or 1/2" NPT, clamping range, temperature range, etc.) must comply with the requirements for PTB ATEX approval in order to ensure protection type EEx d for the TTF350.

For information on the cable gland used, refer to the data sheet and operating instructions.

5.5 Terminal connection diagrams

RTD resistance sensors

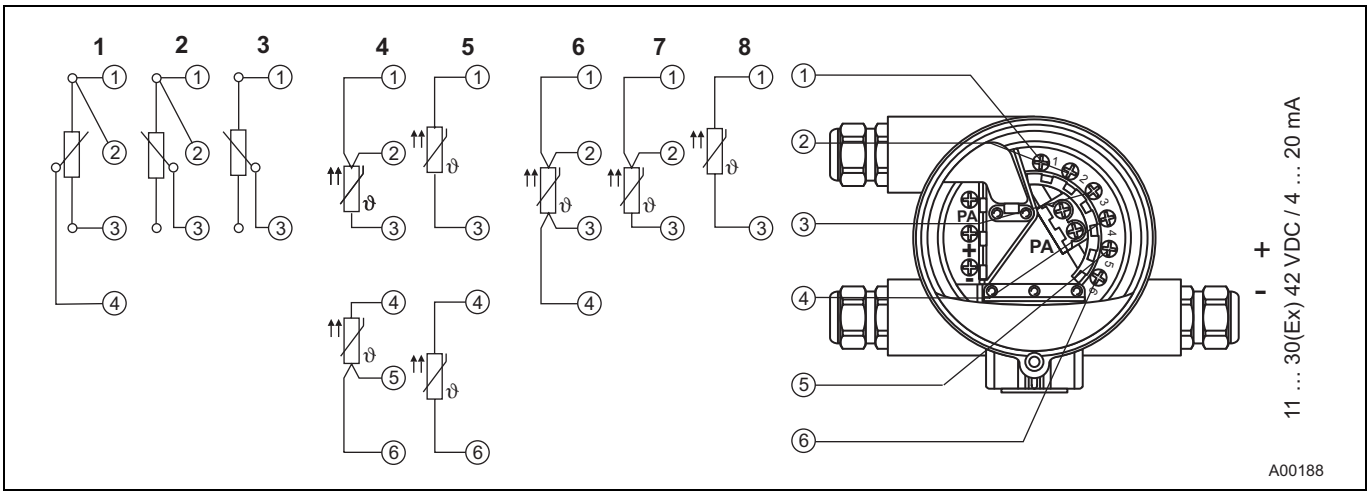


Fig. 7

Potentiometer: 0 … 500 Ω or 0 … 5000 Ω

1 Potentiometer, 4-wire circuit
2 Potentiometer, 3-wire circuit
3 Potentiometer, 2-wire circuit

4 2 x RTD, 3-wire circuit (sensor backup/redundancy, sensor drift monitoring, average value or differential temperature measurement)
5 2 x RTD, 2-wire circuit (sensor backup/redundancy, sensor drift monitoring, average value or differential temperature measurement)

6 RTD, 4-wire circuit
7 RTD, 3-wire circuit
8 RTD, 2-wire circuit

Thermocouples/Voltages

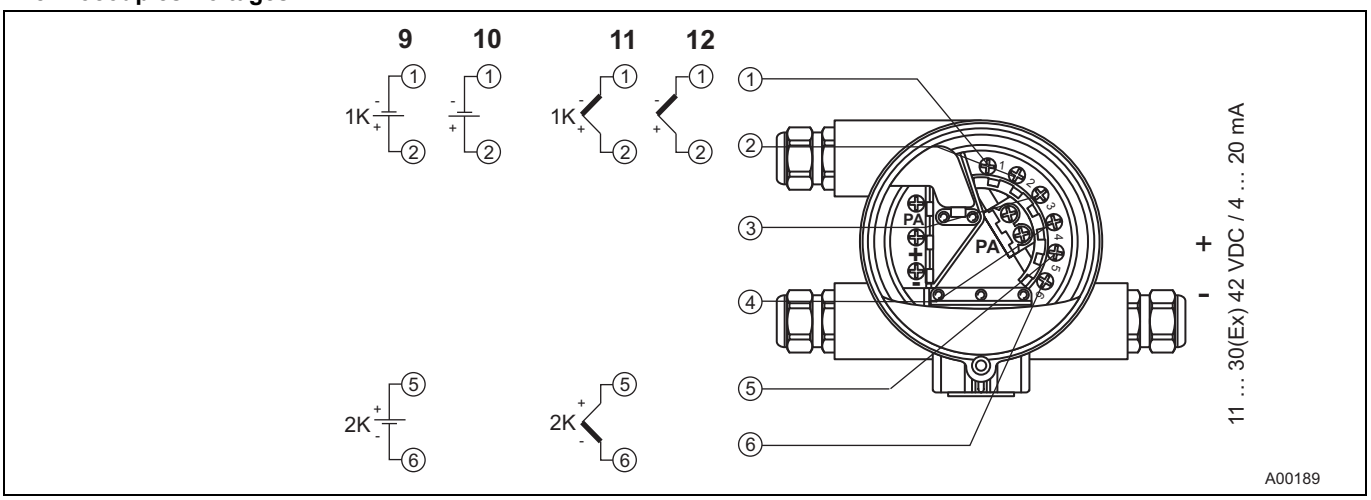


Fig. 8

9 2 x voltage measurement (sensor backup/redundancy, sensor drift monitoring, average value or differential temperature measurement)
10 Voltage measurement
11 2 x thermocouple (sensor backup/redundancy, sensor drift monitoring, average value or differential temperature measurement)
12 Thermocouple

RTD/thermocouples configuration

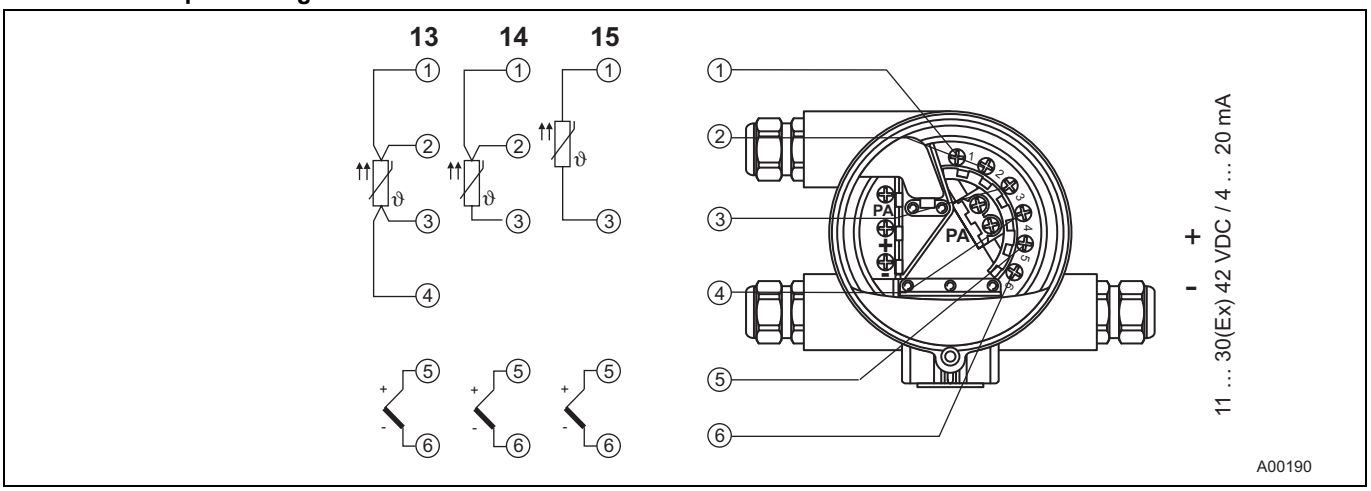


Fig. 9

13 1 x RTD, 4-wire circuit and thermocouple (sensor backup/redundancy, sensor drift monitoring, average value or differential temperature measurement)
14 1 x RTD, 3-wire circuit and thermocouple (sensor backup/redundancy, sensor drift monitoring, average value or differential temperature measurement)
15 1 x RTD, 2-wire circuit and thermocouple (sensor backup/redundancy, sensor drift monitoring, average value or differential temperature measurement)

5.5.1 Standard application

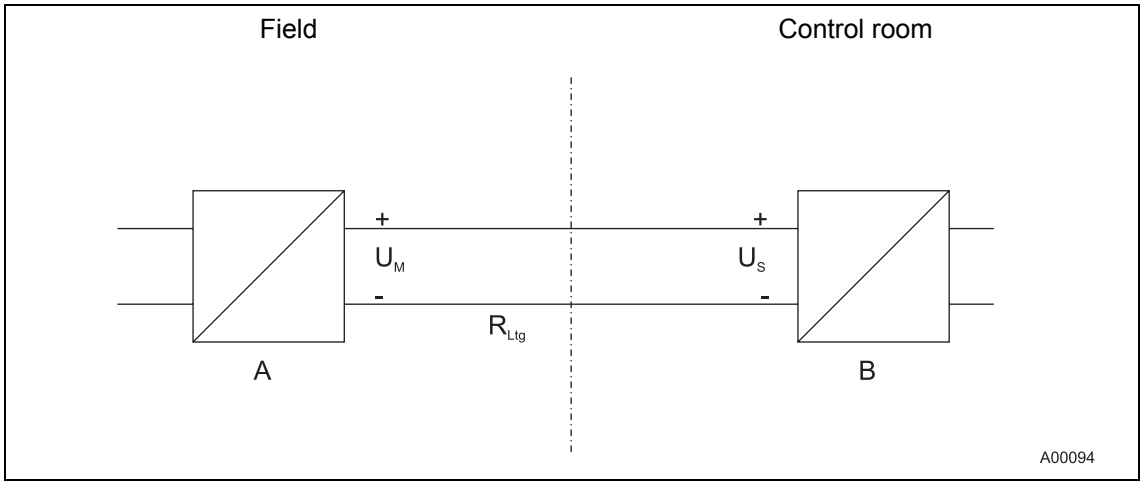


Fig. 10

A Transmitter B Power supply / SPS input with supply

When connecting transmitters and power supplies, observe the following specification:

$U_{Mmin} \leq U_{Smin} + 0.02A \times R_{Ltg}$

Where

U_{Mmin}: Minimum operating voltage of transmitter (refer to technical data for transmitter)

U_{Smin} : Minimum supply voltage of power supply / SPS input

R_{Ltg}: Line resistance between transmitter and power supply

For HART functionality, use power supplies or SPS input cards with HART mark. If this is not possible, the interconnection must have a resistance ≥ 250 Ω (< 1100 Ω).

The signal line can be connected with or without ground. When connecting the ground (minus side), make sure that only one side of the contact is connected to the equipotential bonding system.

5.5.1.1 Standard application with HART functionality

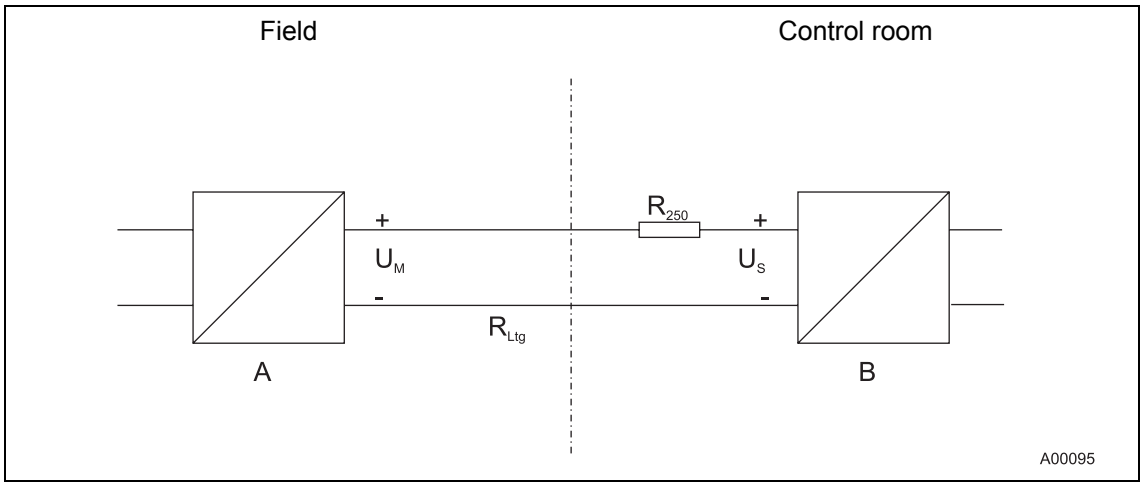


Fig. 11

A Transmitter B Power supply / SPS input with supply

Adding resistance R250 increases the minimum supply voltage:

$U_{Mmin} \leq U_{Smin} + 0.02A \times (R_{Ltg} + R_{250})$

Where

U_{Mmin}: Minimum operating voltage of transmitter (refer to technical data for transmitter)

U_{Smin} : Minimum supply voltage of power supply / SPS input

R_{Ltg}: Line resistance between transmitter and power supply

R_{250}:Resistance for HART functionality

5.5.1.2 Electrical interconnection in explosion risk area

Special interconnections are required for use in hazardous areas depending on the safety requirements.

Intrinsic safety

The Power supply SPS inputs must have corresponding input protection circuits available in order to eliminate a hazard (spark formation). An interconnection inspection must be performed. For proof of the intrinsic safety, the electrical limit values are to be used as the basis for the prototype test certificates of the apparatuses (devices), including capacitance and inductivity values of the wires. The proof of the intrinsic safety is given if the following conditions are fulfilled with comparison of the limit values of the apparatus.

Transmitter (intrinsically safe apparatus)		**Power supply / SPS input** (related apparatus)
U_i	≥	U_o
I_i	≥	I_o
P_i	≥	P_o
$L_i + L_c$ (cable)	≤	L_o
$C_i + C_c$ (cable)	≤	C_o

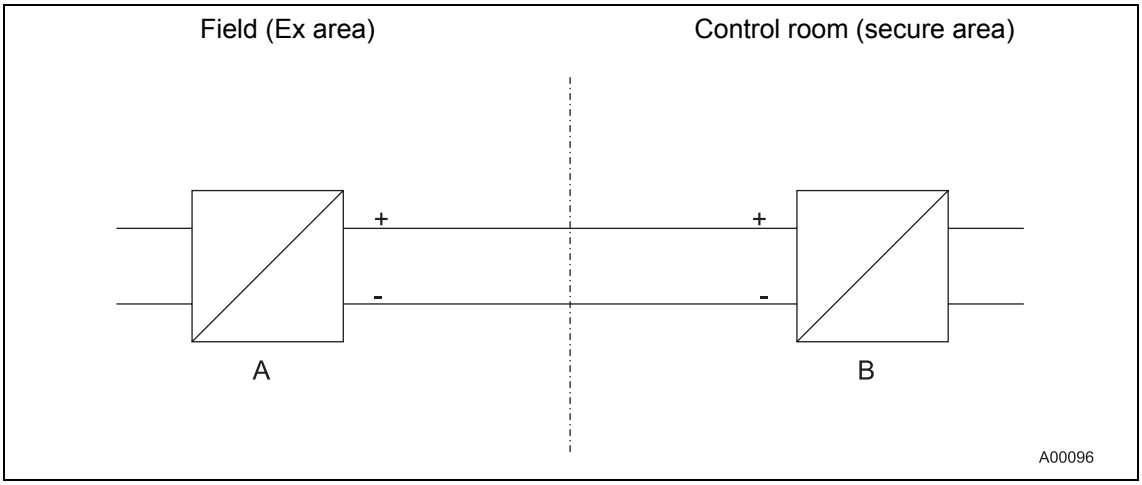


Fig. 12

A Transmitter

B Power supply SPS input

Important

Observe the “Technical specifications” and “Explosion-protection technical data” chapters (see data sheet and/or operating instructions).

5.5.2 Installation in ignition protection areas

Transmitters can be installed in a wide variety of industrial sectors. Systems that requires ignition protection are divided into zones. As a result, different instruments are also required. For additional information, refer to the section “Explosion-protection relevant information” or the data sheet.

5.5.2.1 Zone 0

Transmitter design: II 1G EEx ia IIC T6

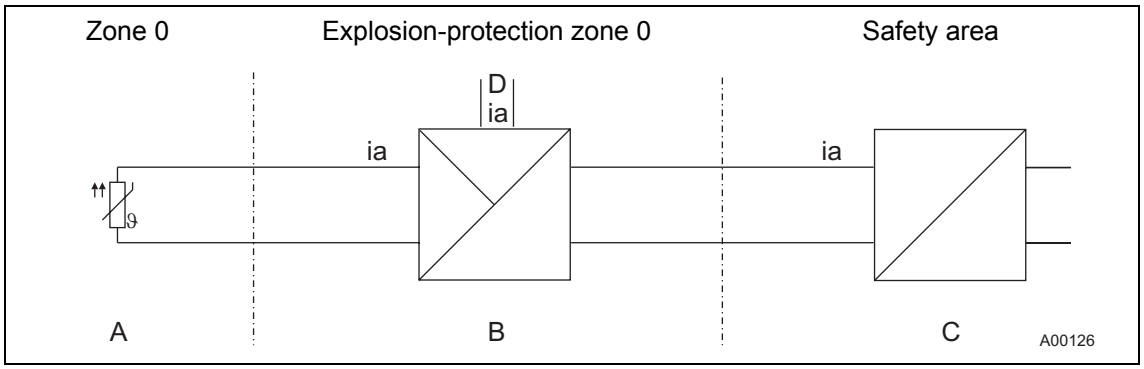


Fig. 13

A Sensor

B TTF350 transmitter

C Power supply [EEx ia]

D HMI interface for LCD display

The input for the power supply must be in EEx ia design.

When using the transmitter in zone 0, make sure you prevent electrostatic charging of the temperature transmitter (observe warnings on equipment).

The sensor must be used by the user in accordance with applicable ignition-protection standards.

5.5.2.2 Zone 1 (0)

Transmitter design: II 2 (1) G EEx [ia] ib IIC T6

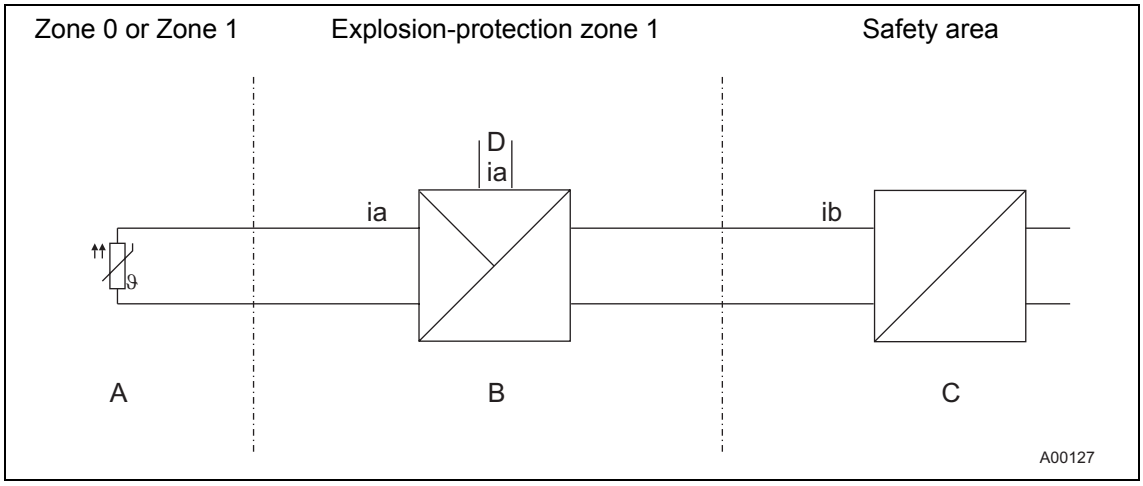


Fig. 14

A Sensor

B TTF350 transmitter

C Power supply [EEx ib]

D HMI interface for LCD display

The input for the power supply must be at a minimum in EEx ib design.

The sensor must be used by the user in accordance with applicable ignition-protection standards. It can be installed in zone 1 or zone 0. For zone 0, the circuit must be in "ia" design.

5.5.2.3 Zone 1 (20)

Transmitter design: II 2G (1D) EEx [iaD] ib IIC T6

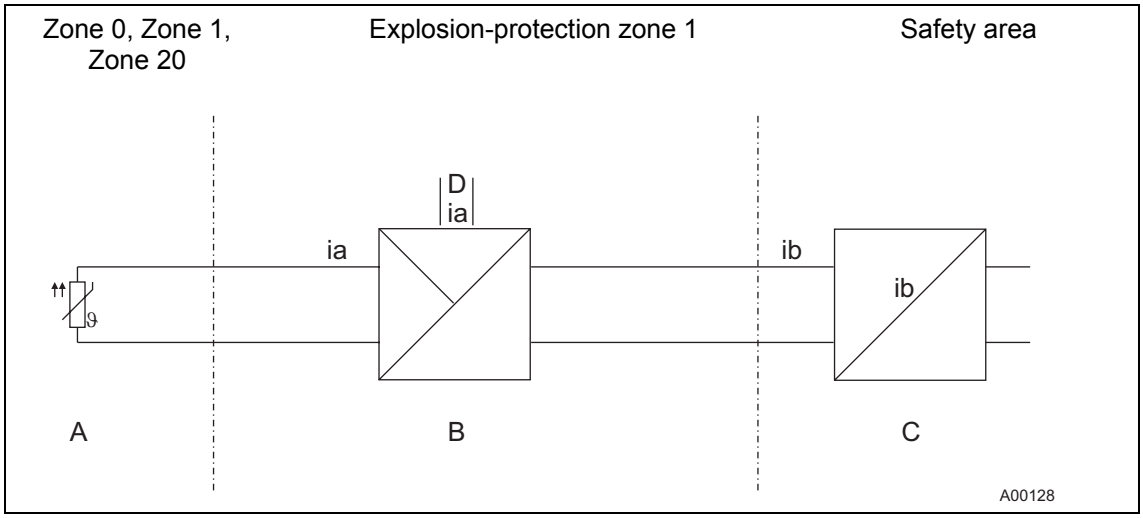


Fig. 15

A Sensor
B TTF350 transmitter
C Power supply [EEx ib]
D HMI interface for LCD display

The input for the power supply must be at a minimum in EEx ib design.

The sensor must be used by the user in accordance with applicable ignition-protection standards. It can be installed in zone 0, zone 1 or zone 20. For zone 0 and zone 20, the circuit must be in "ia" design.

5.5.2.4 Zone 2

Transmitter design: II 3G EEx nA II T6

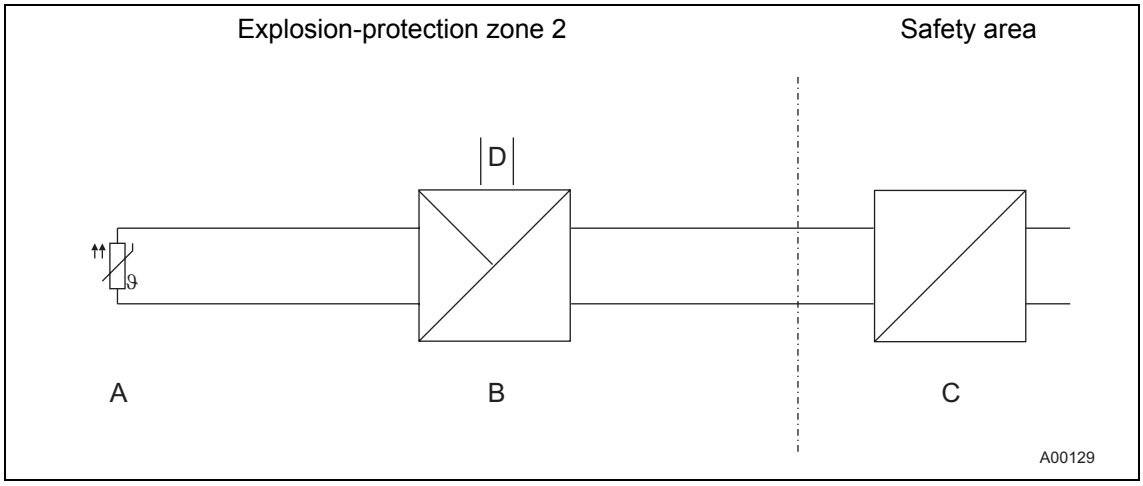


Fig. 16

A Sensor
B TTF350 transmitter
C Power supply
D HMI interface for LCD display

Ensure that in case of a disturbance the supply voltage cannot exceed 40% of the normal voltage.

5.5.2.5 Dust-explosion protection Zone 20:

Transmitter design: ATEX II 1D IP65 T135°C

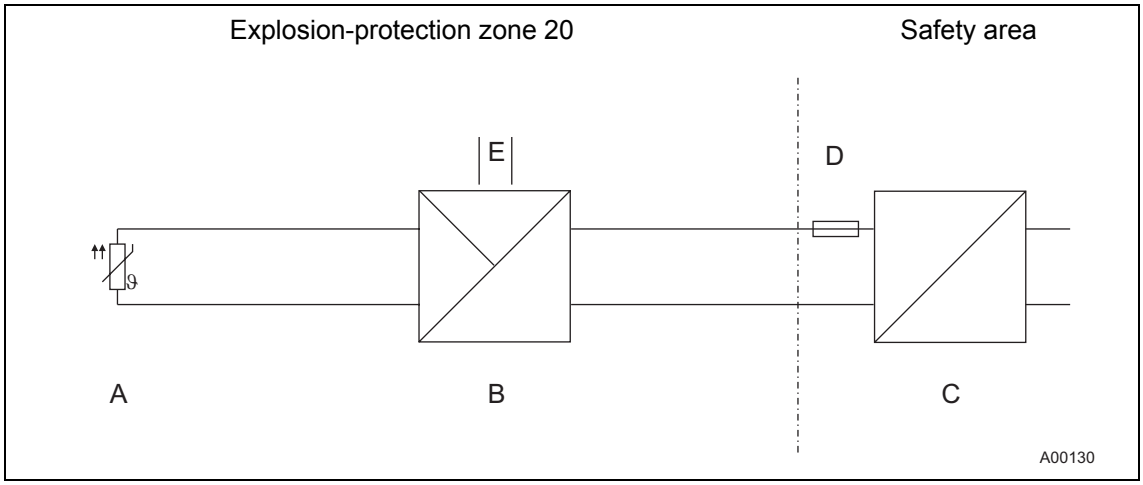


Fig. 17

A Sensor
B TTF350 transmitter
C Power supply
D Fuse, 32 mA
E HMI interface for LCD display

The electric circuit of the transmitter must be limited by an upstream fuse per IEC 127 with a fuse current rating of 32 mA. This is not required if the power supply is in intrinsically safe "ia" design.

5.5.2.6 Dust-explosion protection Zone 0/20

Housing design: ATEX II 1D IP65 T135°C

Transmitter design: ATEX II 1G EEx ia IIC T6

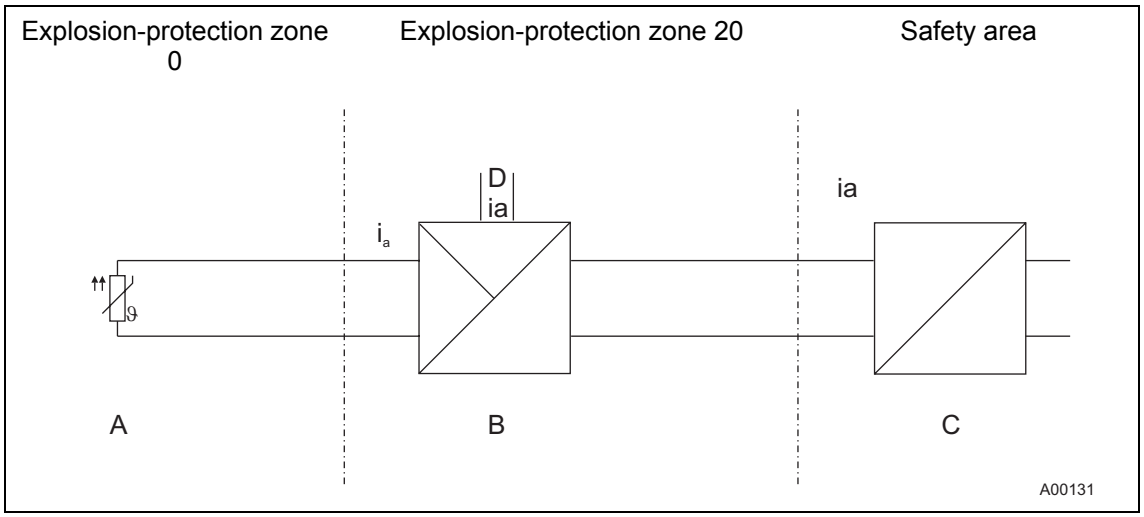


Fig. 18

A Sensor

B TTF350 transmitter

C Power supply

D HMI interface for LCD display

When using the sensor in zone 0, the transmitter must be in EEx ia (category 1G) design.

If the transmitter is designed with intrinsic safety, the power supply must provide an intrinsically safe circuit.

5.5.2.7 Hermetically sealed zone 1

Housing design: ATEX II 2G EEx d IIC T6

Transmitter design: No ignition protection

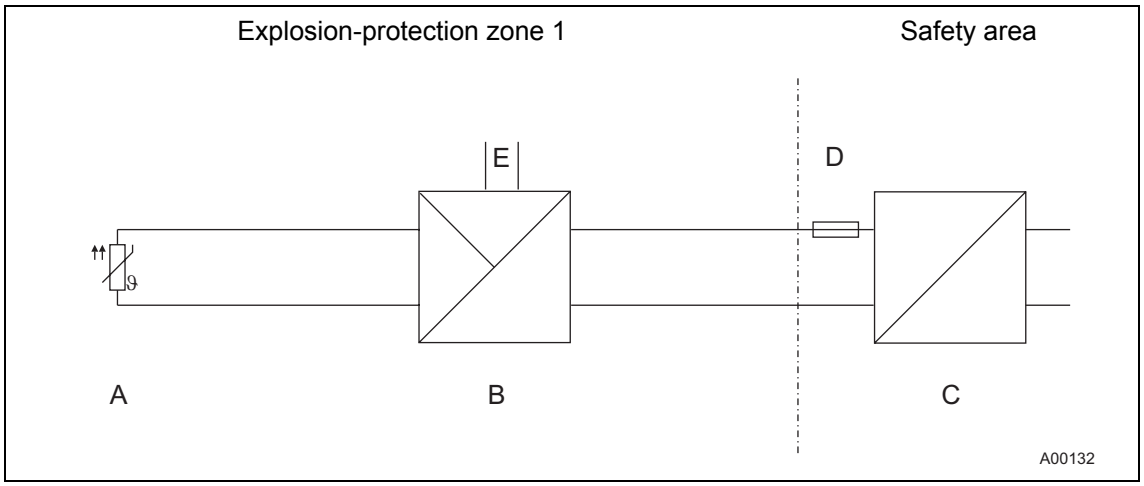


Fig. 19

A Sensor

B TTF350 transmitter in Ex d housing

C Repeater power supply

D Fuse, 32 mA

E HMI interface for LCD display

To achieve the “hermetically sealed” protection class, proper mounting of a specially certified cable gland that complies with the standards and relevant Ex designation is required.

5.5.2.8 Hermetically sealed zone 0

Housing design: ATEX II 2G EEx d IIC T6

Transmitter design: ATEX II 1G EEx ia IIC T6

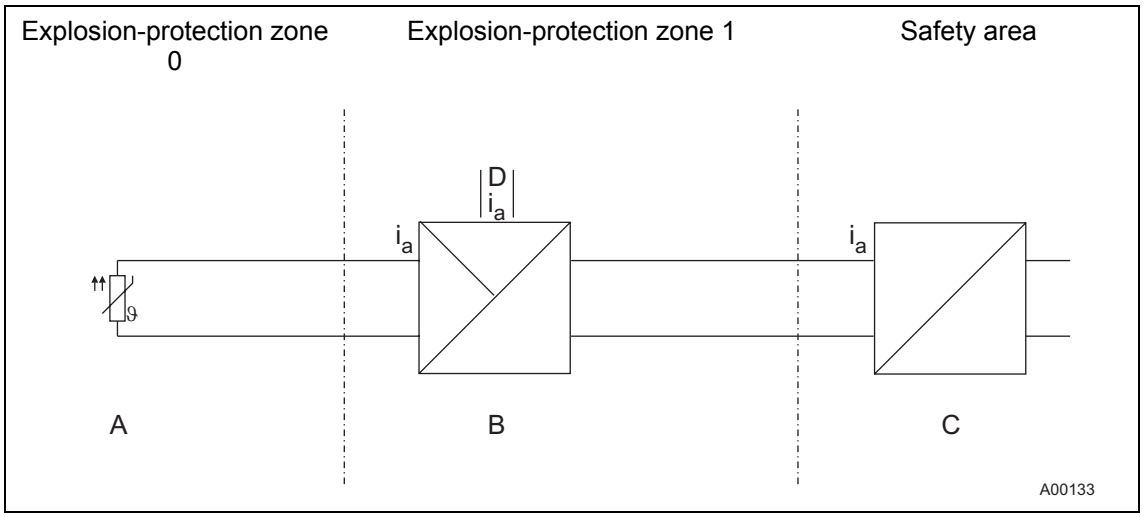


Fig. 20

A Sensor

B TTF350 transmitter in Ex d housing

C Repeater power supply

D HMI interface for LCD display

To achieve the “hermetically sealed” protection class, proper mounting of a specially certified cable gland that complies with the standards and relevant Ex designation is required.

The input for the repeater power supply must be in EEx ia design.

The sensor must be used by the user in accordance with applicable ignition-protection standards. It can be installed in zone 1 or zone 0. For zone 0, the circuit must be in "ia" design.

6 Startup Operation

Important

The transmitter is immediately ready for operation after mounting and installation of the connections. The parameters are set at the factory.

The connected wires must be checked for firm seating. Only firmly seated wires ensure full functionality.

7 Configuration

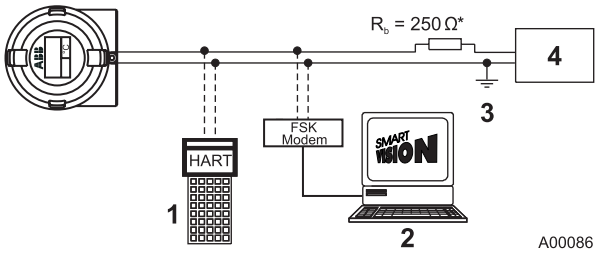
7.1 Configuration options / Communication

There are a variety of configuration options for the transmitter.

- via optional, plug-on LCD display with control buttons.
- via HART protocol and handheld terminal
- via HART protocol with FSK modem, PC and SmartVision configuration software.

via DTM in FDT 1.2 network applications

Configuration via field bus (Profibus), if the superordinate I/O system is HART-enabled (e.g., ABB S800 or S900)



* if necessary

Fig. 21

1 Handheld terminal
2 FDT/DTM technology
3 Ground connection (optional)
4 Power supply (process interface)

HART Communication

Communication with the transmitter is supported by the HART protocol. The communication signal is modulated on both wires for the power supply line and decoded by the transmitter. The electrical connection is provided either by two test pins at the (+) and (–) terminals of the transmitter or by the power supply cable that is installed on-site. The advantage is that power supplies that are part of the industrial plant allow remote configuration.

7.2 Configuration via FDT/DTM technology

Configuration can be performed with any FDT network applications that are approved for use with the DTM (e.g., Smart Vision). The bus can be connected via FSK modem as well as HART + USB, Profibus + remote I/O or HART Multiplexer.

7.3 Configuration via EDD technology

Configuration can also be performed with EDD master applications such as Siemens Simatic, which is approved for use with EDD. In contrast to DTM configuration, EDD has process-dependent, minor limitations such as configuration of a freestyle characteristic.

7.4 Configuration with the handheld terminal

The configuration with the handheld terminal normally takes place at the factory before the installation of the transmitter in an industrial plant.

1. Open the housing of the head-mounted measuring inset.
2. Carefully clamp both test tips of the separate operating control on the contacts in the slotting in front of the + and – connection terminals.
3. Be sure the test terminals are firmly seated.
4. The installation is to be realized according to the figure in the “Configuration types” paragraph.

Important

The connection of the test tips is performed without polarity. Thus, it does not make a difference which test tip is clamped to which + or – connection terminal.

The configuration of the transmitter via the HART protocol can also take place during the normal operation.

7.5 Configuration via the LCD display / configuration software with the control buttons

During operation, the name of the measuring site of the flowmeter primary (tag) and the reading are shown on the LCD display (see section 16).

Important

In contrast to the SmartVision software, the functionality of the transmitter with the LCD display and the control buttons is only partially changeable.

The configuration of the transmitter parameters is described in the section “Configuration with the LCD display and the control buttons” in this manual.

7.5.1 Configuration via the control buttons of the LCD display

The configuration of the transmitter is done using the buttons below the LCD display on the front side of the housing. The buttons and the LCD display are in a protected location under the housing cover with inspection glass. The housing cover must be unscrewed before the transmitter is configured.

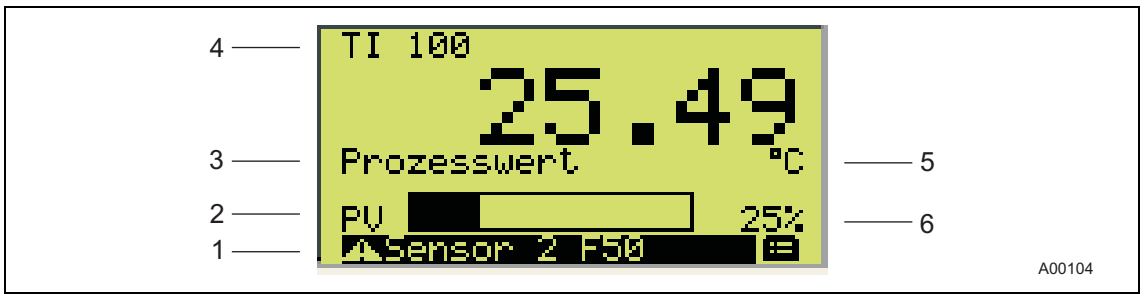


Fig. 22

1 Diagnostic
2 Bar graph
3 Readout
4 HART tag
5 Unit
6 Optional: bar graph in % of configured measuring range

7.5.2 Menu navigation

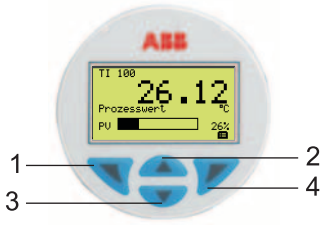


Fig. 23

- The ◂ (1), ▸ (4), ▴ (2) and ▾ (3) buttons are available for the menu-controlled configuration.
- The menu/submenu name is displayed above in the LCD display.
- The number/line of the currently selected menu item is displayed in the upper right of the LCD display.
- A scroll bar is located on the right edge of the LCD display which shows the relative position of the currently selected menu item within the menu.
- Both of the ◂ and ▸ buttons can have various functions assigned to them. The meaning of these buttons is displayed below in the LCD display above the respective button. The following functions are possible.

Button functions ◂	**Meaning**
Exit	Exit menu.
Back	Back one submenu.
Cancel	Exit without saving the selected parameter value.
Next	Select next digit for entering numerical values.

Button functions ▸	**Meaning**
Select	Select submenu/parameter.
Edit	Edit parameter.
OK	Save selected parameter and display stored parameter value.

- You can browse through the menu or select a number within a parameter value using both ▴ or ▾ buttons. The ▸ button selects the desired menu item.
- You can exit a parameter, a submenu or the main menu at any time using the ◂ button.

Calling up the menu

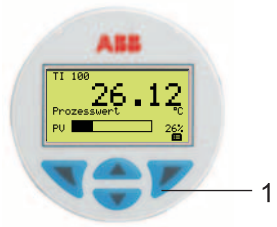


Fig. 24

1 Entering the menu

1. First, the transmitter voltage supply must be switched on. The “ABB connecting …“ display appears after a few seconds. The “Primary VAL“ value is subsequently displayed.
2. A symbol for calling up the menu is located in the LCD display above the ▸ button. By pressing the ▸ button, the configuration menu is called up. The “Config Device” main menu is displayed.

Selecting a menu item/parameter

- The desired submenu must be selected if the menu contains submenus.
- You can only then select a parameter when the corresponding submenu contains configurable parameters, e.g., “Sensor Type”.

Configuring a parameter value

1. If a parameter in a submenu is selected, the current configurable parameter value is displayed.
2. By pressing the ▸ "Edit" button, either all configurable parameter values or a numerical value to be set are displayed. The currently configured parameter value is highlighted.

   Using the "HART tag" example, the alphanumeric operation is also possible. The character position of the tag no. is determined with the ◂ button. The corresponding character can be selected from the character set with the ▲ and ▼ buttons.

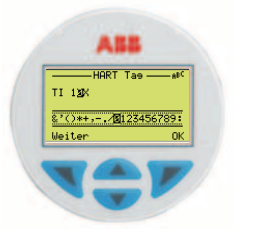


Fig. 25

7.5.3 Example of configuration changes

Output configuration (standard)

Input sensor 1 / sensor type:	PT100 IEC751
Measuring range:	0 … 100 °C
Connection type:	3-wire connection
Fault signaling:	Override / 22 mA
Damping:	Off / 0s
Write Protection:	disabled

Configuration to be set:

Input sensor 1 / sensor type:	Thermocouple type K
Measuring range:	0 ... 1000 °C
Reference point:	internal
Fault signaling:	Override / 22 mA
Damping:	Off / 0s
Write Protection:	activated

Procedure:

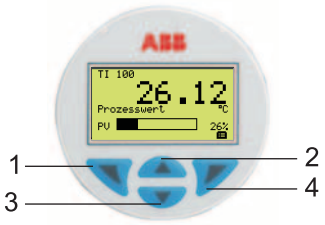


Fig. 26

1. Press the ▸ button to call up the main menu.
2. Use the ▲ (2) and ▼ (3) buttons to mark “Config Device” and confirm via ▸ (4).
3. Select “Input Sensor 1” and confirm via ▸ (4).
4. In the submenu “Input Sensor 1” select the sensor type.
5. Use the ▲ (2) or ▼ (3) buttons to select and confirm “TC Type K (IEC 584)”.
6. “Back” via the ◂ (1) button in the submenu “Input Sensor 1” and menu item “Reference Point”.

Since “internal” is set at the factory, no change is required here.

7. Exit “Reference Point” and return to the menu item “Config. Device” via the ◂ (1) button.
8. Select the subitem “Measuring Range”.

9. In the subitem “Measuring Range”, select the function “Upper Range Value”.

The currently configured URL (100 °C) is displayed.

10. The ▸ (4) “Edit” button can be used to edit the URL. Use the ◂ (1) button to select the individual numbers of the URL and edit these via the ▲ (2) or ▼ (3) buttons.

Important

When changing the LRL or URL, use the ◂ (1) to select the digit position with the current decimal point. The digit position can be changed so that no decimal point appears at this position before the decimal point is set at another position.

If no decimal point is set at another digital position, it can be selected after selecting the digit position by using the ◂ (1) button with the button ▲ (2) or ▼ (3) before or after the configurable digits 0 to 9.

7.5.4 Activating software write protection

1. Confirm “Config Device” via ▸ (4) and select “Write Protection”. Displays the current write protection setting.
2. Use the ▸ (4) “Edit” button to edit the current write protection configuration.
3. Use the buttons ▲ (2) or ▼ (3) to select up to max. 4 alphanumeric characters and confirm via the ▸ (4) button.

Important

Spaces and the number combination 0110 cannot be entered.

4. Write protection “YES” is displayed.

Click the ◂ (1) button three times to exit the configuration mode and display “Reading Display Mode”.

7.5.5 Deactivating software write protection

Access the write protection edit mode according to the example.

In the write protection edit mode, an alphanumeric character chain is displayed.

1. Master password “0110” entered.
2. Use the ▸ (4) “OK” button to confirm.

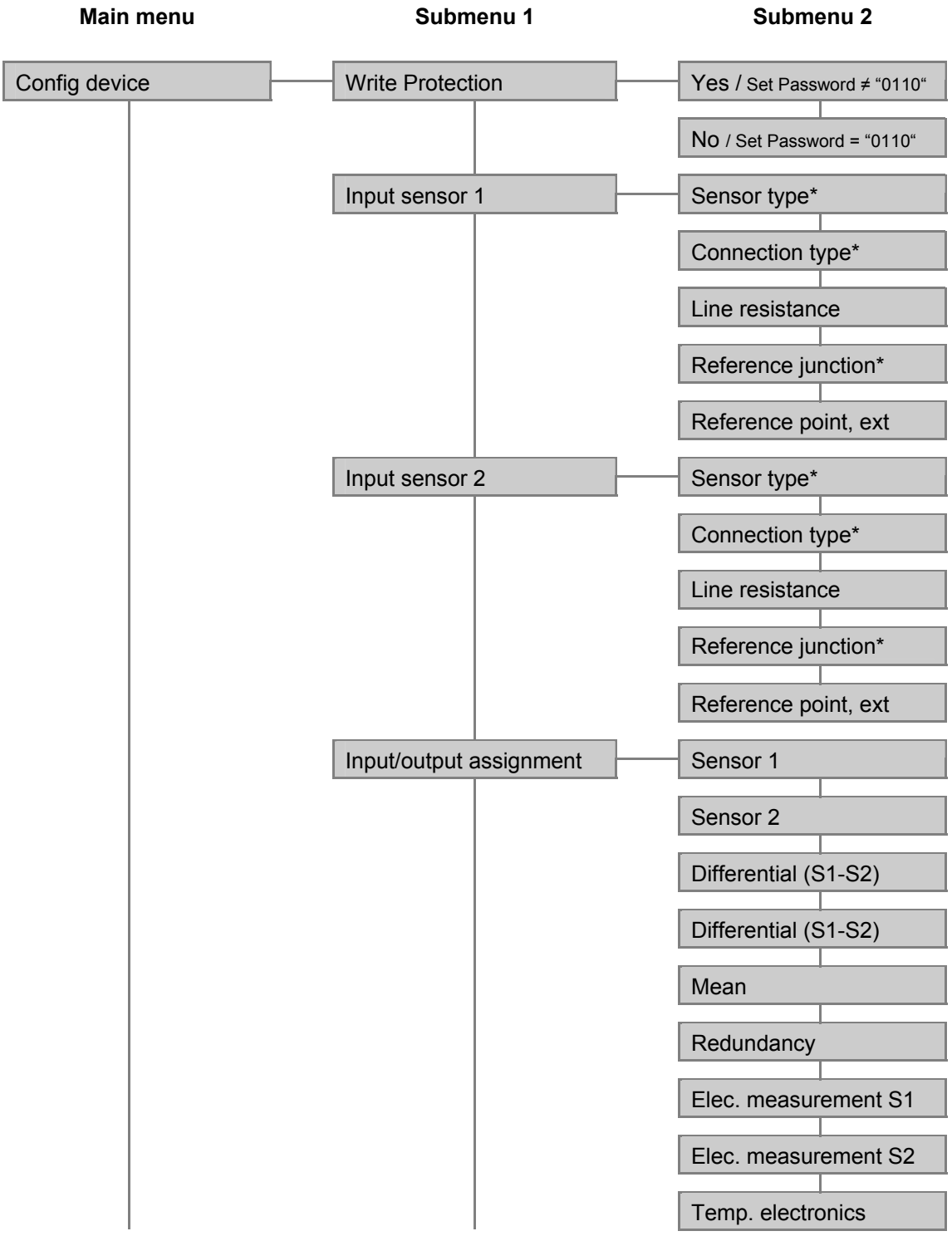
The information “Write protection NO” is displayed.

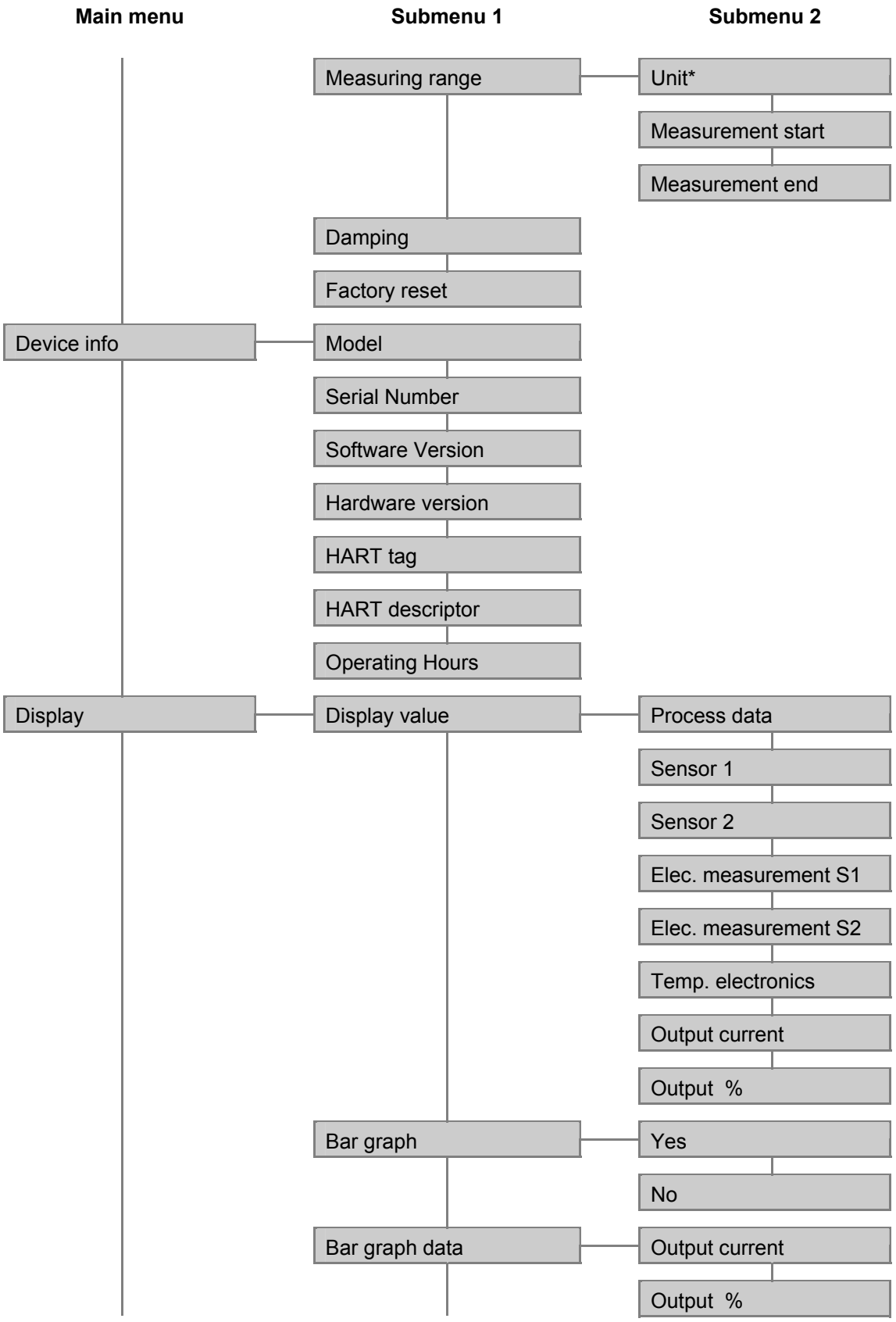
Important

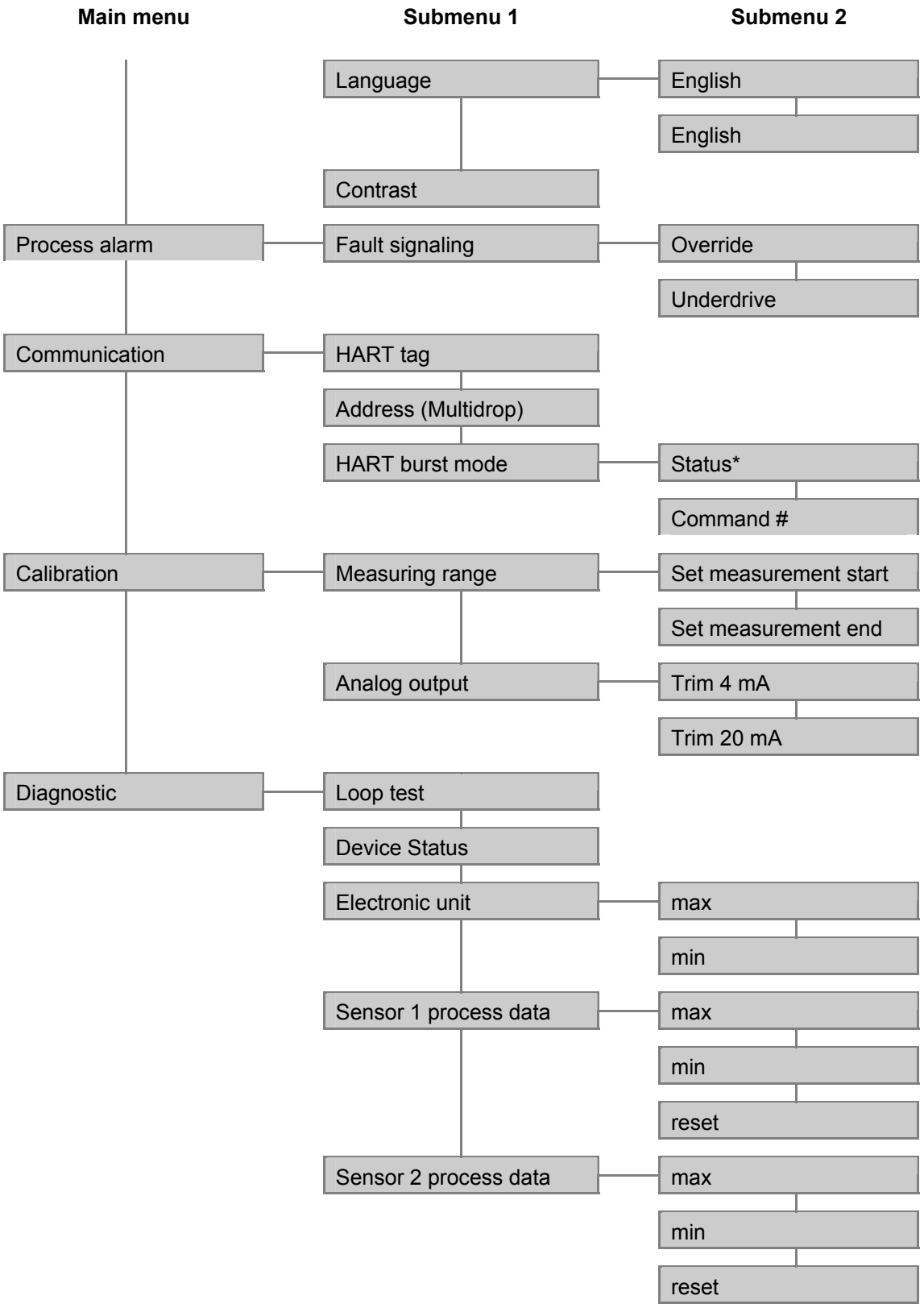
The master password for deactivating write protection cannot be changed.

7.5.6 LCD display / configuration software menu structure

The parameters are structured as a menu. The menu consists of a maximum of three levels. Menu items with the * have additional parameters that are called up in the next section.




Main menu
Submenu 1
Submenu 2
Measuring range
Unit*
Measurement start
Measurement end
Damping
Factory reset
Device info
Model
Serial Number
Software Version
Hardware version
HART tag
HART descriptor
Operating Hours
Display
Display value
Process data
Sensor 1
Sensor 2
Elec. measurement S1
Elec. measurement S2
Temp. electronics
Output current
Output %
Bar graph
Yes
No
Bar graph data
Output current
Output %


Main menu
Submenu 1
Submenu 2
Language
English
English
Contrast
Process alarm
Fault signaling
Override
Underdrive
Communication
HART tag
Address (Multidrop)
HART burst mode
Status*
Command #
Calibration
Measuring range
Set measurement start
Set measurement end
Analog output
Trim 4 mA
Trim 20 mA
Diagnostic
Loop test
Device Status
Electronic unit
max
min
Sensor 1 process data
max
min
reset
Sensor 2 process data
max
min
reset

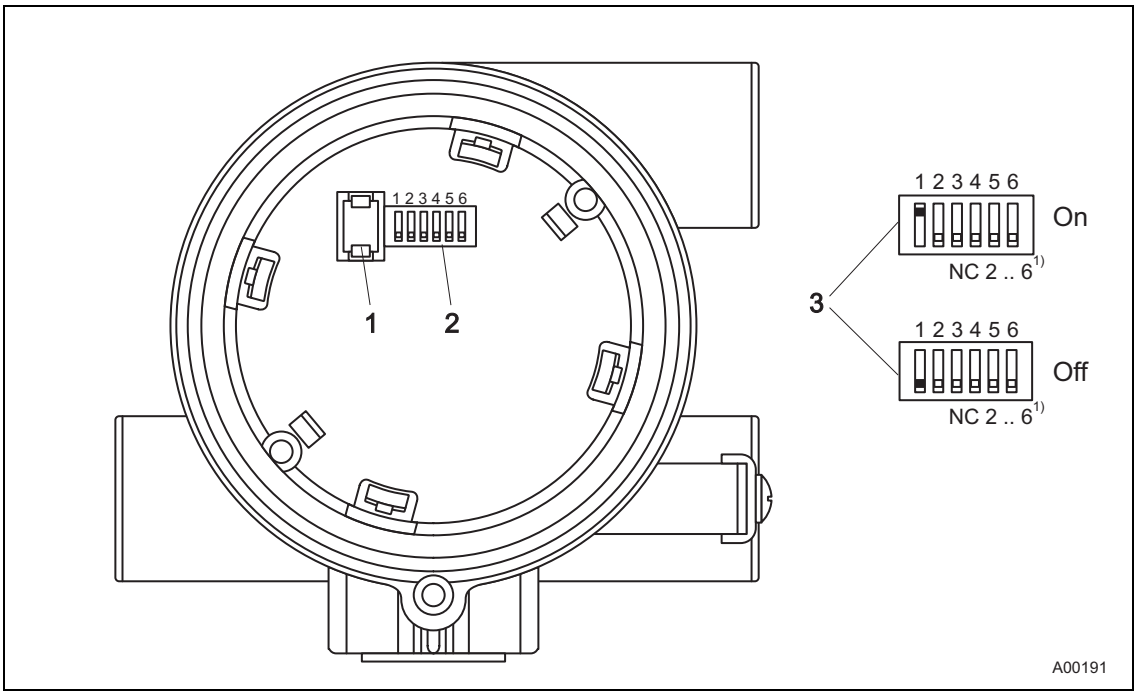
7.6 Hardware write protection via DIP switch

If switch 1 of the 6-pin DIP switch is in the "on" position, hardware write protection is activated and the device cannot be configured.

To configure the device, switch 1 must be in "off" position.

After successfully configuring the device, it is recommended that you activate hardware write protection by moving the switch to the "on" position.

(Devices are generally shipped with hardware write protection deactivated.)



1) NC (not connected) no function

Fig. 27

1 LCD display, configurable interface

2 HW DIP 1

3 Switch position

8 2-sensor input functionality / Dual sensor mode

8.1 2-HART measurement signals

According to the “Connection diagrams” section, equivalent RTD or thermocouple sensors or combinations of both can be attached to the transmitter inputs.

Remote I/O systems such as ABB S900 read out these HART variables on a cyclic basis and provide them to the control system in the form of cyclic process data.

The 4 … 20 mA analog output maps only on sensor value. Users can choose to map sensor value 1 or sensor value 2, the differential based on both, or the average. The value mapped is specified during transmitter configuration, e.g., LCD display in the menu “Config. Device” / submenu “Input/output Assignment”.

8.2 Redundancy / sensor backup

Use two sensors and sensor redundancy mode to increase system uptime.

If sensor 1 fails, the output signal switches bumplessly within the cyclic refresh rate to sensor 2.

In addition, a HART diagnostic message is generated in accordance with Namur NE 107 “Maintenance required / Sensor wire break”.

If redundant sensor 2 fails, a HART signal diagnostic notification is generated.

To minimize the effect on the output signal and increase accuracy in case of a sensor wire break, the average of both sensors is mapped to the analog output in redundancy mode as long as both sensors are available.

Sensor or device failure fault signaling at the analog output signal as required per Namur NE43 / NE107 ensures that the transmitter is capable of signaling "Maintenance required” diagnostic information via HART signal as well as analog signal, using overranging (22 mA) and underranging (3.6 mA).

The signaling of “Maintenance required” diagnostic information according to NE107 when operating with normal 4 … 20 mA analog output is provided by superimposing pulses.

Depending on fault signaling, for 22 mA overload configuration the 4 … 20 mA signal is superimposed on positive 22 mA pulses or with 3.6 mA underload configuration negative 3.6 mA pulses.

The following values can be configured via pulse width parameters:

- A pulse width of 0.5 s … 59.5 s (increment 0.5 s)
- Continuous pulse
- No diagnostic signaling per pulse on the analog output

The specified pulse width refresh rate is 60 seconds.

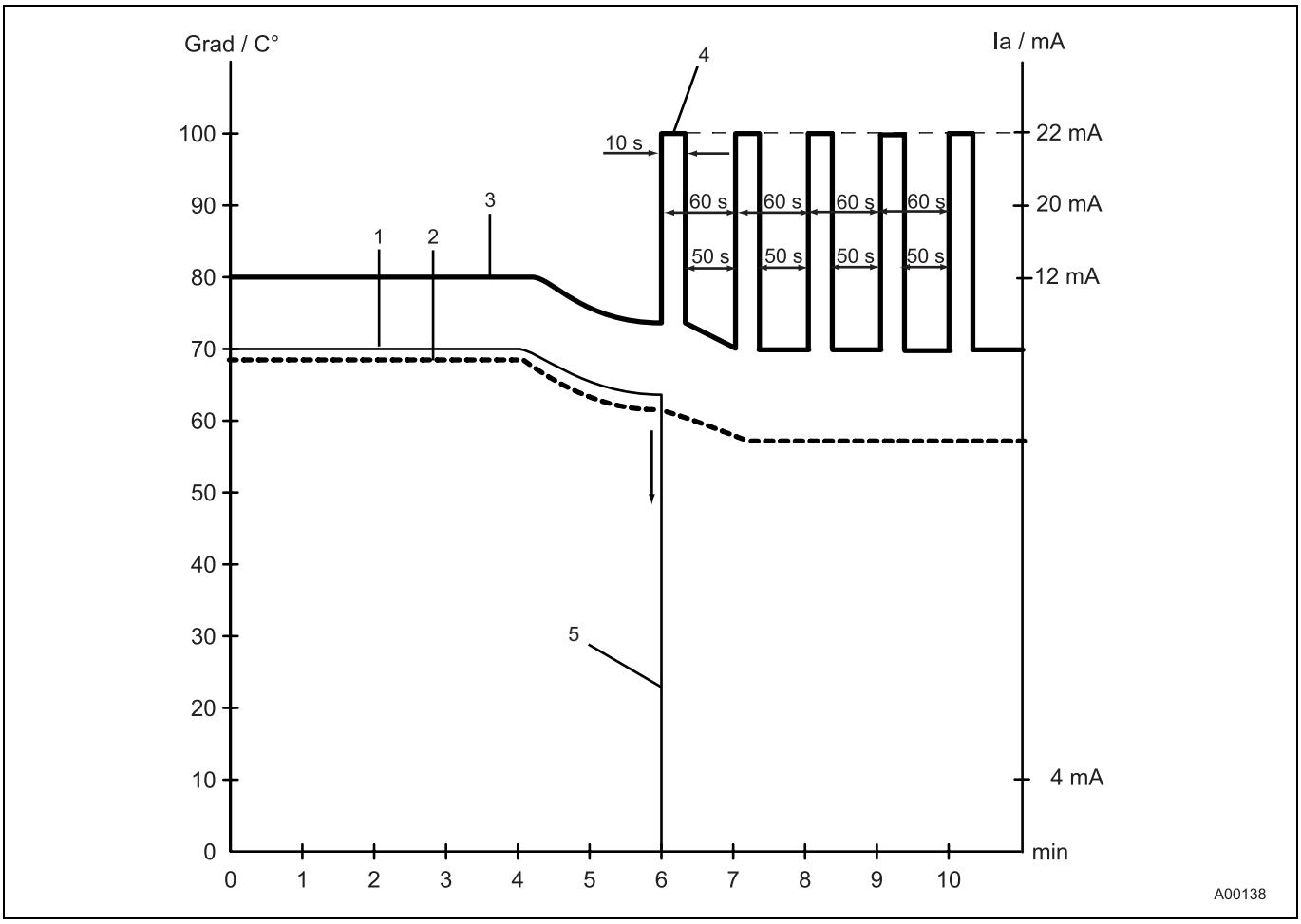


Fig. 28: Alarm pulse signaling in redundancy mode for failure of the temperature characteristic for sensor 2

1 Temperature characteristic for sensor 1 ------

2 Temperature characteristic for sensor 2 ——

3 4 … 20 mA output signal

4 Alarm pulse:

- Off
- On -> Configurable pulse width
- Continuous pulse

5 Wire break temperature characteristic 2

Example:

If a pulse rate of 10 seconds is set, the normal temperature signal of 4 … 20 mA is found at the output due to the pulse width refresh rate of 60 seconds after a 10-second pulse diagnostic alarm signal, e.g., of 22 mA for 50 seconds.

The next cycle begins with a 10-second diagnostic alarm signal and subsequently again after 50 seconds with the normal 4 … 20 mA temperature signal

8.3 Sensor drift detection

When two sensors are connected, an optional sensor drift detection can be activated in redundancy mode, 2-HART measurement signal mode and during averaging.

Activation or configuration of sensor drift detection and analog diagnostic signaling (previously described) can only be performed using TTF350 DTM configuration or EDD-based tools.

Sensor drift detection can be activated for the following two sensor types (for connection diagrams, refer to section 5.5):

- 2 x RTD 2-wire circuit
- 2 x RTD 3-wire circuit
- 2 x resistance measurement / potentiometer 2-wire circuit
- 2 x resistance measurement / potentiometer 3-wire circuit
- 2 x thermocouple
- 2 x voltage measurement
- 1x Pt100 2-wire circuit and thermocouple
- 1x Pt100 3-wire circuit and thermocouple
- 1x Pt100 4-wire circuit and thermocouple

To activate sensor drift detection, the transmitter must first be configured for the abovementioned sensor types. Then the maximum allowable sensor deviation must be configured (e.g., max. 1 °C).

Based on possible marginally different sensor response times, a limit must subsequently be set during which time the sensor deviation must be continuously larger than the max. sensor drift differential value defined at max. 1°C.

If the transmitter records a larger sensor deviation during the defined time period, a HART diagnostic notification “Maintenance required” is generated according to NE107. In addition, diagnostic information is displayed in the LCD display below the measurement value: “Maintenance required” is indicated by an “M” and the error code is also displayed, see section 9 Error messages.

The “Maintenance required” diagnostic information related to sensor drift detection can be signaled as in the event of a sensor failure in redundancy mode as well as pulse alarm signal superimposed on the 4 … 20 mA analog signal as described in further detail in the section on redundancy.

If drift monitoring is used for equivalent sensors (2 x Pt100 or 2 x TC), the average from both sensors is basically mapped to the analog output in redundancy mode.

If a thermocouple is used for Pt100 drift monitoring, the Pt100 sensor (see section 5.5 Connection diagrams) must be connected to channel 1 and the thermocouple sensor to channel 2.

The measurement value from channel 1 (Pt100) is basically mapped at the analog output.

Important

Before configuring the max. allowable sensor deviation for drift detection, it is recommended that you use the TTF350 DTM to align sensor channel 2 with sensor channel 1.

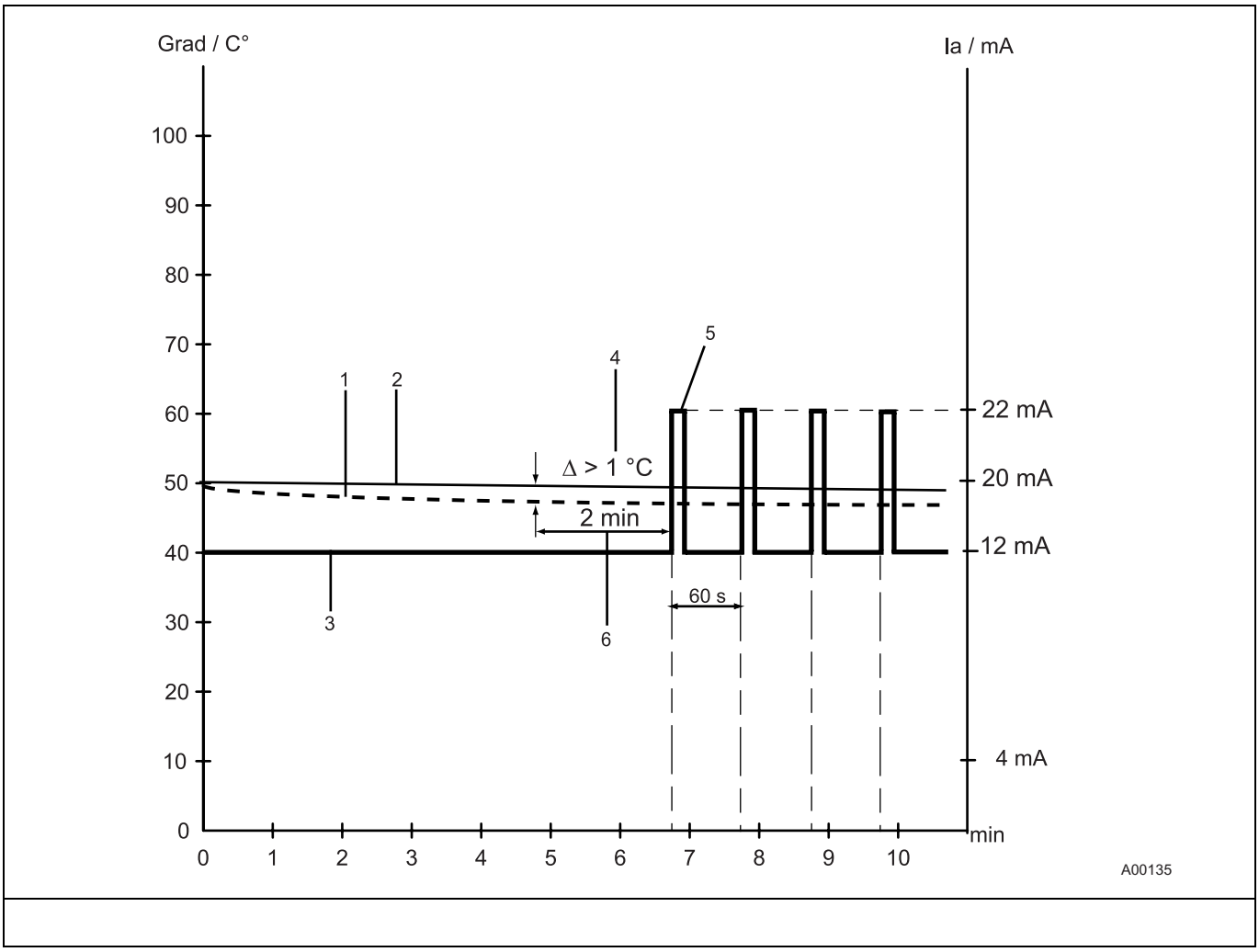


Fig. 29: Alarm pulse signaling during sensor drift overshoot

1 Temperature characteristic for sensor 1 ------

2 Temperature characteristic for sensor 2 ——

3 4 … 20 mA output signal

4 max. sensor drift differential (e.g. Δ > 1 °C)

5 Alarm pulse:

- Off
- On -> Configurable pulse width
- Continuous pulse

6 Sensor drift detection time period (e.g, 2 min.)

8.4 Sensor error compensation (TTF350 DTM Adjust function / in HMI LCD display Calibrate function)

Sensor error adjustment can be performed in the TTF350 DTM by navigating to Device / Maintenance / Adjust / Trim low or Trim high.

For sensor error adjustment, the sensor connected to the transmitter must be brought to the temperature at measurement start / trim low via water quench or oven. It is important to make sure the temperature is balanced and stable.

In the DTM or LCD configuration software, check that the proper adjustment temperature has been entered for the sensor before adjusting the sensor.

Based on the configured adjustment temperature (setpoints) and the digital temperature measured by the transmitter, which is available after linearization in the form of HART temperature information, the transmitter calculates the temperature deviation resulting from the sensor error.

The temperature deviation calculated results during single point adjustment in an offset shift of the linear characteristic output by the linearization module; the values correspond to the HART signal or are sent to the current output.

A sensor error two-point adjustment results in a change of the offset and gradient due to the linear temperature value characteristic output by the linearization module.

A pure sensor offset error can be corrected via the function “Set Measurement Start” or the adjustment function “Trim low”. A non-exclusively sensor offset error can, on the other hand, be corrected only with a two-point adjustment or two-point calibration.

If you enter the temperature value for sensor 1 when adjusting for sensor error on channel 2, then channel 2 is adjusted to the temperature value of sensor 1.

This can occur at a single point (one-point adjustment – sensor – offset – underpressure) as well as at two points (two-point adjustment – sensor – offset and gradient correction).

8.5 D/A analog output compensation (4 and 20 mA trim)

Output compensation is used to correct errors in the power input of the superordinate system.

Analog output compensation for the transmitter can be used to modify the loop current so that the desired value is displayed in the superordinate system.

Error compensation for the superordinate system is possible at the LRL with 4 mA or 20 mA. (Single point error correction: Offset or two-point error correction offset + linear gradient)

D/A analog output compensation can be accessed in the HMI LCD display via the menu path Calibrate / Analog Output / Trim 4/20mA or via TTF350 DTM via the path Device / Maintenance / Adjust.

Prior to analog compensation, it is necessary to determine the loop current values based on iterative entry of current data in simulation mode; the superordinate I/O system displays exactly 4,000 mA, the LRL or 20,000 mA and the URL temperature. The current loop values are to measured via amperemeter and to record .

Simulate the LRL or 4,000 mA +/- 16µA in D/A analog output compensation mode using sensor simulation. Thereafter, enter the iteratively measured current at which the superordinate system displays exactly 4,000 mA or the LRL as adjustment value. Proceed in a similar manner for the URL or 20,000 mA.

The disadvantage of D/A analog output compensation is that the HART signal prior to the D/A conversion without correction differs from the analog output signal after D/A conversion due to the incoming error correction of the superordinate system. As a result, the HART value displayed is slightly different from the output signal current.

8.6 HART variable assignment

Because every HART devices can basically transmit four variables, the measurement value to be transmitted via HART signal can be specified in the menu Device / Configuration when using the TTF350 DTM or EDD for device setup.

The primary variable is mapped to the 4 … 20 mA output as well as the secondary, tertiary and quaternary variables.

The following values can be assigned to variables:

- Elec. input 1
- Elec. input 2
- Sensor 1 process data
- Sensor 2 process data
- Differential sensor 1 – sensor 2
- Differential sensor 2 – sensor 1
- Average of sensor 1 + sensor 2
- Redundancy
- Electronic unit temperature

8.7 Communication / HART tag / Device address

For ease of identification, each HART device features a configurable 8-digit HART tag. Standard devices are come with the HART tag “TI XXX”.

(When storing HART tags with more than 8 digits in the device, use the “Report” parameter, which supports up to 30 characters.)

In addition to the HART tag, each device has a HART address.

This address is set by default to zero, in which state the device operates in HART standard communication mode (point-to-point operation). When an address in the range 1 to 15 is used, the device switches to HART multidrop mode. This operating mode enables users to connect up to 15 devices in parallel to a power supply.

In multidrop mode, an analog output signal that matches the process temperature is not available. The output signal in multidrop mode is, basically, a constant 4 mA and is used exclusively for the power supply.

In multidrop mode, sensor or process data information is available only as a HART signal.

In addition to point-to-point and multidrop modes, the third type of HART communication is burst mode. When burst mode is activated, the device continuously transmits a HART telegram containing reading information approx. every 500 ms without prompting by HART command.

In burst mode as with point-to-point mode, the analog output signal is available and matches the primary variable defined during setup.

8.8 Description of parameters

Device parameters	Description	DTM parameters	HMI LCD display parameters	Effective range	Safety information
Write protection	Activates write protection for the entire device.	<Basic Parameters> <General> <Write Protection>	<Device Setup> <Write Protection> <Password>	HMI Yes: locked Password: ≠ 0110 No: unlocked Enter password: 0110	Must be locked to ensure safety function.
Sensor 1: Sensor model	Select sensor type:	<Device> <Configuration> <Sensor 1 / Sensor Type>	<Device Setup> <Input sensor 1> <Sensor Type>	Pt100 (IEC751) Pt1000 (IEC751) Thermocouple type K (IEC584) Thermocouple type B (IEC584) Thermocouple type C (ASTME988) Thermocouple type D (ASTME988) Thermocouple type E (IEC584) Thermocouple type J (IEC584) Thermocouple type N (IEC584) Thermocouple type R (IEC584) Thermocouple type S (IEC584) Thermocouple type T (IEC584) Thermocouple type L (DIN43710) Thermovoltage – 125…125 mV Thermovoltage –125…1100mV Resistance 0….500 Ω Resistance 0….5000 Ω Pt10 (IEC751) Pt50 (IEC751) Pt200 (IEC751) Pt500 (IEC751) Pt10 (JIS1604) Pt50 (JIS1604) Pt200 (JIS1604) Pt10 (IMIL24388) Pt50 (IMIL24388) Pt100 (MIL24388) Pt200 (MIL24388) Pt1000 (MIL24388) Ni50 (DIN43760) Ni100 (DIN43760) Ni120 (DIN43760) Ni1000 (DIN43760) Cu10 (a=4270) Cu100 (a=4270) Fixpoint-Tabl. 1 Fixpoint-Tabl. 2 Fixpoint-Tabl. 3 Fixpoint-Tabl. 4 Fixpoint-Tabl. 5 Combisensor Cal. Van Dusen 1 Cal. Van Dusen 2 Cal. Van Dusen 3 Cal. Van Dusen 4 Cal. Van Dusen 5	Check safety function
Sensor 1: Type of connection	Sensor connection type relevant for all Pt, Ni, Cu resistance sensor types	<Device> <Configuration> <Sensor 1 / Connection>	<Device Setup> <Input sensor 1> <Connection Type>	2-wire 3-wire 4-wire	Check safety function

Device parameters	Description	DTM parameters	HMI LCD display parameters	Effective range	Safety information
Sensor 1: Line resistance	Sensor resistance relevant for all Pt, Ni, Cu resistance sensor types in 2-wire sensor transmitter connection type	<Device> <Configuration> <Sensor 1 / Line Resistance>	<Device Device> <Input Sensor 1> <Line Resistance>	0 … max. 100 Ω	Check safety function
Sensor 1: Reference point	When using the transmitter reference point: internally relevant for all thermocouples except type B, if thermo/ equalizing conductor is clamped to the transmitter without using the transmitter reference point: without type B, externally fixed transfer of thermo/ equalizing conductor via copper material at constant thermostat temperature	<Device> <Configuration> <Sensor 1 / Reference Point>	<Device Device> <Input Sensor 1> <Reference Point>	internal without externally - fixed	Check safety function
Sensor 1: Reference point ext.	Relevant for external reference point, information on constant external reference point temperature	<Device> <Configuration> <Sensor 1 / Reference Point Temp.>	<Device Device> <Input Sensor 1> <Reference Point Ext.>	-50 ...100°C	Check safety function
Sensor 2: Sensor model	Select sensor type:	<Device> <Configuration> <Sensor 2 / Sensor Type>	<Device Setup> <Input Sensor 2> <Sensor Type>	Like sensor 1	Safety function relevant and requires check of following input/output assignments: Sensor 2 Differential (S1-S2) Differential (S1-S2) Mean Redundancy Elec. reading 2
Sensor 2: Type of connection	Sensor connection type relevant for all Pt, Ni, Cu resistance sensor types	<Device> <Configuration> <Sensor 2 / Connection>	<Device Setup> <Input Sensor 2> <Connection Type>	Like sensor 1	Safety function relevant and requires check of following input/output assignments: Sensor 2 Differential (S1-S2) Differential (S2-S1) Mean Redundancy Elec. reading 2

Device parameters	Description	DTM parameters	HMI LCD display parameters	Effective range	Safety information
Sensor 2: Line resistance	Sensor resistance relevant for all Pt, Ni, Cu resistance sensor types in 2-wire sensor transmitter connection type	<Device> <Configuration> <Sensor 1 / Line Resistance>	<Device Setup> <Input Sensor 2> <Line Resistance>	Like sensor 1	Safety function relevant and requires check of following input/output assignments: Sensor 2 differential (S1-S2) differential (S2-S1) average redundancy elec. reading 2
Sensor 2: Reference point	When using the transmitter reference point: internally relevant for all thermocouples except type B, if thermo/equalizing conductor is clamped to the transmitter without using the transmitter reference point: without type B, externally fixed transfer of thermo/equalizing conductor via copper material at constant thermostat temperature	<Device> <Configuration> <Sensor 1 / Reference Point>	<Device Setup> <Input Sensor 2> <Reference Point>	Like sensor 1	Safety function relevant and requires check of following input/output assignments: Sensor 2 differential (S1-S2) differential (S2-S1) average redundancy elec. reading 2
Sensor 2: Reference point ext.	Relevant for externally fixed reference point, information on constant external reference point temperature	<Device> <Configuration> <Sensor 1 / Reference Point Temperature>	<Device Setup> <Input Sensor 2> <Reference Point Ext.>	Like sensor 1	Safety function relevant and requires check of following input/output assignments: Sensor 2 Differential (S1-S2) Differential (S2-S1) mean redundancy elec. reading 2
Sensor 1	Parametrized measuring range of sensor 1 is mapped to the 4 … 20 mA analog output	<Device> <Configuration> <Measurement Type / Primary Variable (PV)>	<Device Setup> <Input/output assignment>	Sensor 1	Check safety function
Sensor 2	Parametrized measuring range of sensor 2 is mapped to the 4 … 20 mA analog output	<Device> <Configuration> <Measurement Type / Primary Variable (PV)>	<Device Setup> <Input/output assignment>	Sensor 2	Check safety function

Device parameters	Description	DTM parameters	HMI LCD display parameters	Effective range	Safety information
Differential (S1-S2)	The differential temperature from sensor 1 minus sensor 2 is mapped to the 4 … 20 mA analog output according to the parametrized measuring range (0°C … max. differential temperature)	<Device> <Configuration> <Measurement Type / Primary Variable (PV)>	<Device Setup> <Input/output assignment>	Differential (S1-S2)	Check safety function
Differential (S2-S1)	The differential temperature from sensor 2 minus sensor 1 is mapped to the 4 … 20 mA analog output according to the parametrized measuring range (0°C … max. differential temperature)	<Device> <Configuration> <Measurement Type / Primary Variable (PV)>	<Device Setup> <Input/output Assignment>	Differential (S1-S2)	Check safety function
Mean	The average of two independent sensors 1 and 2 is mapped to the 4 … 20 mA analog output according to the parametrized measuring range	<Device> <Configuration> <Measurement Type / Primary Variable (PV)>	<Device Setup> <Input/output assignment>	Mean	Check safety function
Redundancy	With two functioning sensors for a measuring inset, the average is mapped to the 4 … 20 mA analog output for the parametrized measuring range. When one sensor fails, the temp signal for the functioning sensor switches bumplessly and is mapped to the 4 … 20 mA output.	<Device> <Configuration> <Measurement Type / Primary Variable (PV)>	<Device Setup> <Input/output assignment>	Redundancy	Check safety function
Elec. reading S1	The 4 … 20 mA output signal matches the Ω or mV signal of sensor 1	<Device> <Configuration> <Measurement Type / Primary Variable (PV)>	<Device Setup> <Input/output assignment>	Elec. reading S1	Check safety function
Elec. reading S2	The 4 … 20 mA output signal matches the Ω or mV signal of sensor 2	<Device> <Configuration> <Measurement Type / Primary Variable (PV)>	<Device Setup> <Input/output assignment>	Elec. reading S2	Check safety function

Device parameters	Description	DTM parameters	HMI LCD display parameters	Effective range	Safety information
Temp. electronics	The 4 ... 20 mA output signal matches the electronic unit temperature	<Device> <Configuration> <Measurement Type / Primary Variable (PV)>	<Device Setup> <Input/output assignment>	Temp. electronics	Check safety function
Unit	Select the unit of measure for the sensor	<Device> <Parametrize> <Measuring Range of PV / Unit>	<Device Setup> <Measuring Range> <Unit>	°C, °F, °R, K, user, mV, Ω, mA	Depending on sensor type
Measurement start	Defines the sensor measurement start	<Device> <Parametrize> <Measuring Range of PV / Lower Range Value>	<Device Setup> <Measuring Range> <Lower Range Value>	Depending on sensor type	Depending on sensor type
Measurement end	Defines the sensor measurement end	<Device> <Parametrize> <Measuring Range of PV / Upper Range Value>	<Device Setup> <Measuring Range> <Upper Range Value>	Depending on sensor type	Depending on sensor type
Damping	Configurable condensation 63 % output signal damping value	<Device > <Parametrize> <Voltage Output / Damping>	<Device Setup> <Damping>	0 ... 100 s	Depending on sensor type
Factory reset	Configuration data is reset to factory settings for Pt100 3-wire, 0 ... 100°C damping off, override, adjustment data (trim high/low and DAC adjustment values are reset to factory settings)	<Device> <Maintenance> <Reset to Factory Setting>	<Device Setup> <Factory Setting>	Yes / OK	Safety function for potential risk all configuration and adjustment data are reset to the factory default
Device reset	Configuration data is reset to factory setting for Pt100 3-wire, 0 … 100°C damping off, override	<Device> <Maintenance> <Device Reset>			Safety function for potential risk configuration data is reset to the factory default
Override	Generates a 22 mA high alarm signal for sensor or device errors	<Device> <Parametrize> <Current Output / Output with Fault>	<Process Alarm> <Fault Signaling>	Override	Check safety function
Underdrive	Generates a 3.6 mA low alarm signal for sensor or device errors	<Device> <Parametrize> <Current Output / Output with Fault>	<Process Alarm> <Fault Signaling>	Underdrive	Check safety function
HART tag	Defines HART tag name	<Device> <Maintenance> <Poll Address / Tag>	<Communication> <HART Tag>	8 characters, alphanumeric	Check safety function

Device parameters	Description	DTM parameters	HMI LCD display parameters	Effective range	Safety information
Address (Multidrop)	Defines communication type	<Device> <Maintenance> <Poll Address / Tag>	<Communication> <Address (Multidrop)>	Address = 0 conforms to HART operating mode: Point-to-point communication, 4 ... 20 mA output signal address = 1 ... 15 conforms to HART multidrop operating mode output signal const. 4 mA only the digital HART readings are available	Check safety function
HART burst mode			<Communication> <HART Burst Mode> <Status> <Communication> <HART Burst Mode> <Command>	on off Primary Var. Current + % Range Current + Dyn. Var.	Check safety function
Set measurement start	Temperature correction for specified / simulated sensor LRL value to desired LRL temperature value	<Device> <Maintenance> <Adjust>	<Calibrate> <Measuring Range>	Trim low or Set Lower Range Value> ok	Check safety function
Set measurement end	Temperature correction for specified / simul. Sensor measurement value at desired URL temperature value	<Device> <Maintenance> <Adjust>	<Calibrate> <Measuring Range>	Trim high or Set Upper Range Value> ok	Check safety function
Trim 4 mA	Output signal correction for specified / simul. Sensor LRL at 4,000 mA setpoint	<Device> <Maintenance > <Adjust /DAC compensation fixed for zero point at 4 mA>	<Calibrate> <Analog Output>	Analog current measurement value input min. 3,5 ... max. 4,5 mA	Check safety function
Trim 20 mA	Output signal correction for specified / simul. Sensor URL at 20,000 mA setpoint	<Device> <Maintenance > <Adjust /DAC compensation fixed for amplification at 20 mA>	<Calibrate>- <Analog Output>	Analog current measurement value input min. 19.5 ... max. 20.5 mA	Check safety function
Simulation	Output signal simulation corresponding to the value specified	<Device> <Simulation>	<Diagnostic> <Loop Test>	3.5 ... 23.6 mA	Check safety function

Device parameters	Description	DTM parameters	HMI LCD display parameters	Effective range	Safety information
Drift detection: enabled	activated Sensor drift detection	<Device > <Parametrize> <enabled>		on off	Check safety function
Drift detection: max. sensor differential	Value at which sensor drift signaling occurs, if overshoot is longer than the limit time period is present	<Device > <Parametrize> <Max. Sensor Differential>		... Degrees C; ...°F, ...mV, ... Ohm	Check safety function
Drift detection: Sensor drift Limit time period	Time period during which the max. sensor differential must be overshot, before sensor drift signaling occurs	<Device > <Parametrize> <Limit time period>		.....minutes	Check safety function
Analog alarm pulse Maintenance Demand signaling: Response for maintenance need	Analog alarm pulse signaling with configurable pulse width for sensor maintenance needs (e.g., failure of a sensor in redundancy mode or overshoot of max. sensor drift differential)	<Device > <Parametrize> <Output current/ Response for Maintenance Needs>		Off Pulse width: >0....59.5 s continuous	Check safety function

* Safety check is performed acc. to SIL safety information based on the document SM/TTX3X/SIL-DE

8.8.1 Factory settings

The transmitter is preconfigured at the factory. The following tables contain the values of the individual parameters.

Menu	Designation	Parameter	Factory setting
Device Config	Write Protect	-	No
	Input Sensor 1	Sensortype	Pt100 (IEC751)
		R-Connection	3-wires
		Measured Range Begin	0
		Measured Range End	100
		Unit	°C
		Damping	Off
Process Alarm		Fault signaling	Override 22 mA
	Input Sensor 2	Sensortype	Off
	In-output Assignment	-	Sensor 1
	HART Tag	-	-
	HART Descriptor	-	TIXXX
Display	Main Operator View	-	Process Variable
	Bargraph Enable	-	Yes
	Bargraph View	-	Output %
	Language	-	English
	Contrast	-	50 %
Communication	HART Burstmode	Status	Off

9 Error messages

The following list contains the error messages for the LCD display.

	Device Status	DIAG. NO.	Source of Error	Error correction
Device	F	1	Device defective.	Replacing the device.
Device	S	2	Above/below ambient temperature.	Check environment, possibly reposition measuring point.
Device	F	3	EEPROM defective.	Replacing the device.
Device	M	4	Electronics overload.	Reset to factory settings, notify service of error message.
Device	F	5	Memory error.	Reset to factory settings, notify service of error message.
Device	I	7	HMI inserted.	Status info, no error.
Device	I	8	Device write-protected.	Status info, no error.
Device	I	9	EEPROM busy.	Status info, no error.
Device	F	12	Sensor input defective (communication).	Replacing the device.
Device	F	13	Sensor input defective (error).	Replacing the device.
Device	F	14	Sensor input defective (ADC error).	Replacing the device.
Communication	C	32	Diagnostic simulation mode	No error, diagnostic info, measurement OK.
				Sensor
Sensor 1	F	34	Measuring error.	Check sensor connection.
Sensor 1	F	35	Sensor short-circuit.	Check sensor connection.
Sensor 1	F	36	Wire break.	Check sensor connection.
Sensor 1	F	37	Above sensor range.	Check measuring limits.

	Device Status	DIAG. NO.	Source of Error	Error correction
Sensor 1	F	38	Below sensor range.	Check measuring limits.
Sensor 1	I	41	Single point calibration active.	Status info, no error.
Sensor 1	I	42	Two point calibration active.	Status info, no error.
				Sensor
Sensor 2	F	50	Measuring error.	Check sensor connection.
Sensor 2	F	51	Sensor short-circuit.	Check sensor connection.
Sensor 2	F	52	Wire break.	Check sensor connection.
Sensor 2	F	53	Above sensor range.	Check measuring limits.
Sensor 2	F	54	Below sensor range.	Check measuring limits.
Sensor 2	I	57	Status info.	Status info, no error.
Sensor 2	I	58	Status info.	Status info, no error.
Application	F	65	Configuration defective.	Check configuration: A) Incorrect device. B) Measuring span is too small. Incorrect configuration data.
Application	M	66	No sensor detected at sensor 1 in redundancy configuration.	Check connection.
Application	M	67	No sensor detected at sensor 2 in redundancy configuration.	Check connection.
Application	M	68	Sensors exceeded specified drift window	Calibrate sensors
Application	C	71	Reconfiguration is running.	Status info, no error.
Application	F	72	Incorrect application.	Check configuration, connections; reset to factory settings; notify service.
Application	I	74	Calibration of analog output active.	Status info, no error.

	Device Status	DIAG. NO.	Source of Error	Error correction
Application	C	75	Analog output in simulation.	Status info, no error.
Application	S	76	Above range.	Check parameters: A) Above sensor range. Measuring span is too small.
Application	S	77	Limit HIGH HIGH.	Upper limit value: Alarm.
Application	S	78	Limit LOW LOW.	Lower limit value: Alarm
Application	S	79	Limit HIGH.	Upper limit value: Warning.
Application	S	80	Limit LOW.	Lower limit value: Warning.

Explanations per NE107

Designation	Description
I	OK or Information
C	Check Function
S	Off Specification
M	Maintenance Required
F	Failure

10 Additional TTF350 DTM diagnostic information

Configuration changed

Important

The transmitter indicates that the parameters or configuration data has changed (HART: Configuration changed flag). After intentional or desired reconfiguration, the notification can be acknowledged via the <Reset> button.

10.1 Long-term monitoring

The transmitter saves the highest and lowest values for the electronic unit temperature as well as readings from sensor 1 and sensor 2 in a failsafe memory (“Drag Indicator”).

Supply voltage	Current supply voltage measured at the clamps of the transmitter in volts (+/- 5%).
Max. elec. temp.	Highest detected internal temperature in °C that the transmitter was subjected to. This value cannot be reset.
Min. elec. temp.	Lowest detected internal temperature in °C that the transmitter was subjected to. This value cannot be reset.
Max. reading for sensors 1-2	Highest reading at sensor 1 or 2. When changing the sensor type (e.g., Pt100 to thermocouple type K), the value is reset automatically.
Min. reading for sensors 1-2	Lowest reading at sensor 1 or 2. When changing the sensor type, the value is reset automatically.
Reset	The drag indicators for the sensor readings are reset to the current measurement value.

10.2 Operating hour statistics

Operating hours	Total hours since commissioning that power has been switched on for transmitter.
Operating hours per electronic unit temperature	The operating hours are categorized according to the measured internal temperature of the transmitter. Due to rounding and frequently switching the device on and off, the total of the individual values may differ slightly from the value displayed by the counter for operating hours. Values in the fields on the far left and right display operation of the transmitter outside the specified range. In this event, acknowledged properties of the transmitter might be limited, in particular, with respect to accuracy and service life.

11 Maintenance / Repair

11.1 General information

For transmitters that are used as intended under normal operation, no maintenance is required.

No on-site repair or replacement of electronic parts is planned.

Warning! Risk of explosion!

Faulty transmitters may not be placed into operation by the user.

Repairs must be performed in the production plant.

11.2 Cleaning

When cleaning the exterior of meters, make sure that the cleaning agent used does not corrode the housing surface and the seals.

12 Explosion-protection relevant information

12.1 TTF350-E1 .. H: (intrinsic safety)

Approved for use in zone 0.

Designation:

- II 1G EEx ia IIC T6 (Zone 0)
- II 2 (1) G EEx [ia] ib IIC T6 (zone 1 [0])
- II 2 G (1D) Ex [iaD] ib IIC T6 (zone 1 [20])

Important
The Ex or ignition-proof designation is provided on the name plate.

EC prototype test certificate: Refer to PTB 05 ATEX2017 X.

Temperature table

Temperature class	Permissible ambient temperature range	
	Device category 1 use	Device category 2 use
T6	-50 … 44 °C	-50 … 56 °C
T5	-50 … 56 °C	-50 … 71 °C
T4	-50 … 84 °C	-50 … 85 °C

Safety-relevant data

Intrinsically safe EEx ia IIC explosion protection

	Supply circuit	Measurement current circuit / passive transducer (RTD)	Measurement current circuit / active transducer (RTD)	Display interface
Max. voltage	U_i = 30 V	U_o = 6,5 V	U_o = 1,2 V	U_o = 6,2 V
Short-circuit current	I_i = 130 mA	I_o = 25 mA	I_o = 50 mA	I_o = 65,2 mA
Max. power	P_i = 0,8 W	P_o = 38 mW	P_o = 60 mW	P_o = 101 mW
Internal inductance	L_i = 0,5 mH	L_i = 0 mH	L_i = 0 mH	L_i = 0 mH
Internal capacitance	C_i = 5 nF	C_i = 49 nF	C_i = 49 nF	C_i = 0 nF
Maximum permissible external inductance		L_o= 5 mH	L_o = 5 mH	L_o= 5 mH
Maximum permissible external capacitance		C_o= 1,55 µF	C_o= 1,05 µF	C_o= 1,4 µF

12.2 TTF350 -E2 .. H: (non-incendive)

Approved for use in zone 2/22.

Designation:

- II 3 G EEx n A II T6
- II 3 D IP 65 T 135 °C

Important
The Ex or ignition-proof designation is provided on the name plate.

ABB statement of conformity in accordance with ATEX directive.

Temperature table

Temperature class	Permissible ambient temperature range
T6	-50 °C … 56°C
T5	-50 °C … 71°C
T4	-50 °C … 85°C

CSA and FM

Intrinsically safe

FM	Class I, Div. 1 + 2, Groups A, B, C, D T6 Class II, Groups E, F, G; Class III Class I, Zone 0, AEx ia IIC T6 Product variant: TTF350-L4 .. H Control drawing: TTF350-L4 .. H
CSA	Class I, Div. 1 + 2, Groups A, B, C, D Class II, Groups E, F, G; Class III Product variant: TTF350-R4 .. H Control drawing: TTF350-R4 .. H

Non-incendive

FM	Class I, Div. 2, Groups A, B, C, D (Class II, Groups E, F, G; Class III Product variant: TTF350-L5 .. H Control drawing:TTF350-L5 .. H (2 pages)
CSA	Class I, Div. 2, Groups A,B,C,D (Class II, Groups E, F, G; Class III Product variant: TTF350-R5 .. H Control drawing: TTF350-R5 .. H (2 pages)

Dust-explosion protection:
TTF350-D1 … : Dust-explosion protection
Dust / Zone 20:
Designation: "Ex mark" II 1 D IP 65 T 135°C
EC prototype test certificate BVS06 ATEX E029

TTF350-D2 .. H: Dust-explosion protection + Intrinsic safety
Dust / Zone 20 + Gas / Zone 0:
Designation: "Ex mark" II 1 D IP 65 135°C
"Ex mark" II 1G EEx ia IIC T6
EC prototype test certificate BVS06 ATEX E029
EC prototype test certificate PTB 05 ATEX 2017 X
EC prototype test certificate ZELM 07 ATEX 0331 U

Flameproof protection
TTF350-E3…: flameproof protection
Zone 1:
Designation: "Ex mark" II 2G EEx d IIC T6
EC prototype test certificate ATEX
TTF350-E4 .. H: flameproof protection + intrinsic safety
Zone 1:
Designation: "Ex mark" II 2G EEx d IIC T6
"Ex mark" II 1G EEx ia IIC T6
EC prototype test certificate ATEX
EC prototype test certificate PTB 05 ATEX 2017 X
EC prototype test certificate ZELM 07 ATEX 0331 U

Explosion-proof protection
TTF350-L3 … FM Explosion-proof
XP,NI, DIP Class I, II, III, Div. 1 + 2, Groups A-G, factory sealed
Control drawing: TTF350-L3
TTF350-R3 … CSA Explosion-proof
XP,NI, DIP Class I, II, III, Div. 1 + 2, Groups A-G, factory sealed
Control drawing: TTF350-R3

13 Approvals

13.1 TTF350

CE mark

The TTF350 including type B LCD display / configuration software meets all requirements for the CE mark in accordance with IEC 61326 (2002).

Namur

The TTF350 including type B LCD display / configuration software complies with NAMUR NE 21 (02/2004).

Ignition protection

The TTF350 meets requirements for ATEX, FM and CSA. For additional information, refer to the section "Explosion-protection relevant information".

SIL: Functional safety (optional)

acc. to IEC 61508.
Device with certificate of conformity for use in safety-relevant applications, including SIL Level 2. For additional information, refer to the SIL safety manual for the TTH300 / TTF300 / TTF350.

14 Technical data

14.1 Input

14.1.1 Resistance

RTD resistance thermometer
Pt100 in acc. with DIN IEC 60751, JIS, MIL, Ni in acc. with DIN 43760, Cu
Resistance measurement
0 … 500 Ω
0 … 5000 Ω
Sensor connections
2-, 3-, 4-wire circuit
Connecting cables
2-, 3-, 4-wire max. sensor line resistance (R_W) for each wire 50 Ω in acc. with NE 89 (March 2003);
(3-wire balanced, 2-wire circuit compensation up to 100 Ω sensor total line resistance)
Measurement current
< 300 µA
Sensor short-circuit
< 5 Ω (for RTD)
Sensor wire break (temperature resistance measurement 2-, 3-, 4-wire)

Measuring range 0 ... 500 Ω	> 0.6 ... 10 kΩ
Measuring range 0 ... 5 kΩ	> 5.3 ... 10 kΩ

Corrosion detection in accordance with NAMUR NE 89
3-wire resistance reading > 50 Ω
4-wire resistance reading > 50 Ω

14.1.2 Thermocouples/Voltages

Types
B, E, J, K, L, N, R, S, T, U, C, D
Voltages
-125 mV ... 125 mV
-125 mV ... 1100 mV
Connecting cables
Max. sensor line resistance (R_W) for each line 1.5 kΩ, total 3 kΩ
Sensor wire break monitoring in accordance with Namur NE 89
pulsed with 1 µA outside the measurement interval

Thermoelement measurement	5.3 ... 10 kΩ
Voltage measurement	5.3 ... 10 kΩ

Input resistance
> 10 MΩ
Internal reference junction
Pt100, DIN IEC 60751 Cl. B
(no jumpers necessary)
Customer specific curve, 32-tie points
Resistance measurement up to max. 5 kΩ
Voltages up to max. 1.1 V
Sensor matching
via Callendar van Dusen coefficients
via table of 32 sampling points
via single point (offset adjustment)
via two point adjustment
Input functionality
1 Sensor
2 Sensors:
mean measurement
Differential measurement: Zero point where Ia = 4 mA
Differential measurement: Zero point where Ia = 12 mA
Sensor redundancy

Sensor fault signaling

RTD sensor:	Short circuit and wire break
Linear resistance measurement:	Wire break
Thermocouple:	Wire break
Linear voltage measurement:	Wire break

14.2 Output

Transmission characteristics
temperature linear
resistance linear
voltage linear
Output signal
Configurable 4 ... 20 mA (standard)
Configurable 20 ... 4 mA
(NE43 dynamic range: 3,8 ... 20.5 mA)
Simulation mode
3,5 ... 23,6 mA
Induced current consumption
< 3,5 mA
Maximum output current
23,6 mA
Configurable error current signal

override	22 mA (20.0 … 23.6 mA)
underdrive	3.6 mA (3.5 … 4.0 mA)

Configurable analog alarm pulse if
maintenance required.
In redundancy mode when a sensor fails and/or in
drift mode if the maximum sensor drift value will exceeded.
(For details, refer to OI TTF350.)

Two configurable warning limits
HART-Signal/diagnostic bit information
Two configurable alarm limits
HART-Signal/diagnostic bit information

14.3 Power supply (polarity safe)

(2-wire technique; power lines = signal lines)

Supply voltage

Non ignition-proof application with or without LCD display:

U_S = 11 ... 42 V DC

Ignition-proof applications with or without LCD display:

U_S = 11 ... 30 V DC

Max. permissible residual ripple for supply voltage

Max. permissible ripple for supply voltage during communication in accordance with HART FSK "Physical Layer" specification, version 8.1 (08/1999) Section 8.1

Undervoltage detection

$U_{Terminal-Mu}$ < 10 V results in I_a = 3.6 mA

Max. load

R_{Load} = (supply voltage – 11 V) / 22 mA

Max. load Ω) depending on supply voltage (V DC)

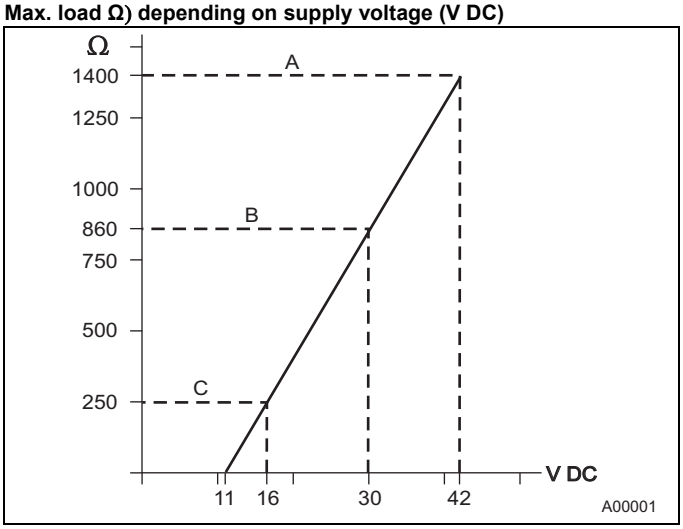


Fig. 30

A TTF350,

B TTF350 in EEx ia design

C HART communication - resistor

Max. power consumption

P = U_S x 22 mA

e.g., U_S = 24 V → P_{max} = 0.528 W

15 General information

Galvanic isolation (input/output)	3.5 kV AC (approx. 2.5 KV DC) 60 s (insulation test voltage)
MTBF time	28 years at 60 °C ambient temperature
Input filter	50 / 60 Hz
Switch-on delay	< 10 s (I_a ≤ 3.6 mA during starting cycle)
Warm-up time	5 min.
Ramp-up time t90	400 … 1000 ms
Readingupdated[1)]	10/s with 1 sensor, 5/s with 2 sensors
Output filter	Digital filter 1st order: 0 ... 100 s

[1)] depending on sensor type and sensor circuit

15.1 Ambient conditions

Ambient temperature:

Standard: -40 … 85 °C / -40 … 185 °F

Optional: -50 … 85 °C / -58 … 185 °F

For use with LCD display HMI type B:

-20 … 70 °C / -4 … 158 °F

For ignition-proof design, see prototype test certificate PTB 05 ATEX 2079 X.

Transport / storage temperature:	-40 … 85 °C / -40 … 185 °F
Climate class:	Cx (-40 … 85 °C / -40 … 185 °F, 5 … 95% relative humidity) DIN EN 60654-1
Max. permissible humidity:	99% relative humidity IEC 60068-2-78
Vibration resistance*:	10 … 2000 Hz at 5 g acc. to IEC 60068-2-6
Shock*:	gn = 30 in accordance with IEC 60068-2-27
Earthquake resistance:	Acc. to EN1473
Salt fog:	acc. to IEC 60068-2-11
Protection class:	IP66 and IP67; NEMA 4X, ENCL 4X

* applies to operation and transport

15.2 Electromagnetic compatibility

Emitted interference in accordance with IEC 61326 (2002) and Namur NE21 (02/2004)

15.3 Interference immunity

Interference immune in accordance with IEC 61326 (2002) and Namur NE21 (02/2004)

Pt100: Measuring range 0 ... 100 °C, span 100 K

Type of test	Testing accuracy	Influence
Burst to signal/data lines	2 kV	< 0.5%
Static discharge		
• Contact plate (indirect)	8 kV	no
• Supply terminals[1)]	6 kV	no
• Sensor terminals[1)]	4 kV	no
Radiated field 80 MHz ... 2 GHz	10 V/m	< 0.5%
Coupling 150 kHz … 80 MHz	10 V	< 0.5%
Surge between the lines	0.5 kV	no malfunction
Line to earth	1 kV	no malfunction

[1)] Air discharge (at 1 mm distance)

16 LCD-display

Dual function: LCD display with TTF350 configuration options

16.1 Features of the LCD display

- Transmitter-controlled graphic (alphanumeric) LCD display
- Character height, mode-dependent
- Sign, 4 digits, 2 decimal places
- Bar graph display
- Plug in to 4 positions each 90° apart
- Display options:
  - Sensor 1 process data
  - Sensor 2 process data
  - Sensor 1 electrical (Ω / mV)
  - Sensor 2 electrical (Ω / mV)
  - Electronics/ambient temperature
  - Output/current
  - Output %
- Display diagnostic information related to transmitter and sensor status

16.1.1 Technical data of LCD display

Temperature range: -20 … 70 °C
(-50 … -20 °C or 70 … 85 °C no function)

Humidity: 0 … 99% relativ humidity IEC 60068-2-78

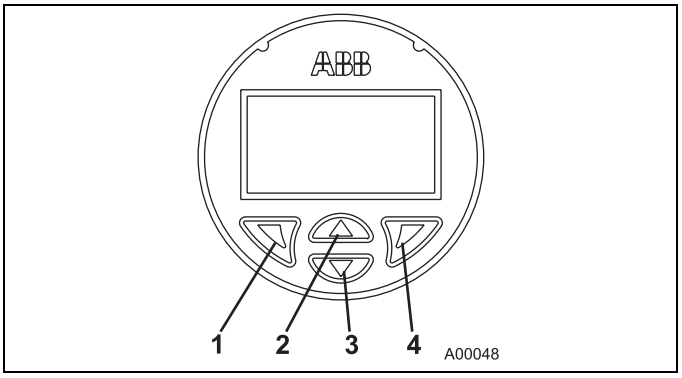


Fig. 31

1 Exit/Cancel
2 Scroll back
3 Scroll forward
4 Select

16.2 Configuration function of LCD display

- Configurable TTF350 transmitter parameters per display:
  All parameters
  (sensor/type circuit, measuring range, leakage current signal, etc.)
  except: table-based sensor and freestyle characteristics, Callendar van Dusen coefficients, warning and alarm limits, drift parameters, NE107 "Maintenance required" alarm pulse signal
- Software write protection for TTF350 configuration

16.3 LCD display HMI ignition-proof type B (intrinsically safe)

Approved for use in zone 0.

Designation:
- II 1G EEx ia IIC T6

Important
The Ex or ignition-proof designation is provided on the name plate.

EC prototype test certificate: ZELM 07 ATEX 0331 U

Temperature table

Temperature class	Permissible ambient temperature range	
	Device category 1 use	Device category 2 use
T6	-40 … 40 °C	-40 … 40 °C
T5	-40 … 55 °C	-40 … 55 °C
T4	-40 … 85 °C	-40 … 85 °C

For the ambient temperature range from -50 °C to -20°C, additional mechanical protection is required.

Safety-relevant data
Intrinsically safe EEx ia IIC explosion protection

	Supply circuit
Max. voltage	U_i = 9 V
Short-circuit current	I_i = 65,2 mA
Max. power	P_i = 101 mW
Internal inductance	L_i = 0 mH
Internal capacitance	C_i = 342 nF

17 Appendix

17.1 Permits and certifications

	Symbol	Description
Ignition protection approvals		The Ex label indicates a device that complies with the directive 94/9/EC.
CE mark		The CE mark indicates that the device complies with the following directives and their basic safety requirements: • CE mark on the name plate of transmitter - Conforms with EMV directive 89/336/EWG - Conforms with low voltage directive 73/23/EWG • For ignition-protection applications: Conforms with explosion-protection directive 94/9/EC (ATEX 95) By placing the CE mark on its devices, ABB Automation Products GmbH declares its conformance with these directives.

Important
All declarations of conformity and certificates are available as a separate document in the download area of ABB Automation Products GmbH.
www.abb.com/temperature

17.2 Additional documents

- Getting started manual (CI/TTF350)
- Data sheet (DS/TTF350)

Statement about the contamination of devices and components

The repair and/or maintenance of devices and components will only be performed when a completely filled out explanation is present.

Otherwise, the shipment can be rejected. This explanation may only be filled out and signed by authorized specialist personnel of the operator.

Customer details:

Company:	
Address:	
Contact person:	Telephone:
Fax:	E-Mail:

Device details:

Type:	Serial no.:
Reason for the return/description of the defect:	

Was this device used for working with substances which pose a threat or health risk?

☐ Yes ☐ No

If yes, which type of contamination (please place an X next to the applicable items)

biological	☐	corrosive/irritating	☐	combustible (highly/extremely combustible)	☐
toxic	☐	explosive	☐	other toxic substances	☐
radioactive	☐				

Which substances have had contact with the device?

1.
2.
3.

We hereby certify that the devices/parts shipped were cleaned and are free from any dangerous or poisonous materials.

City, Date	Signature and company stamp

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www.abb.com/temperature

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